

Biography

- Doctorate in Systems and Computer Engineering (COPPE/UFRJ) in 2011
- Professor at EIC CEFET/RJ
 - DEPIN
 - COINFO
- Permanent professor at
 - Postgraduate Program in Computer Science (PPCIC)
 - Postgraduate Program in Production and Systems Engineering (PPPRO)
- Member of IEEE, SBC, ACM, and INNS
- Institutional representative of SBC



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IX EIC Workshop

- Workshop has more than 200 participants
- Many interesting themes
- Confirmed talks:
 - Oct 19 4pm Pesquisa e Extensão na EIC: De onde viemos? Quem somos? Para onde iremos? – Carmen de Queiroz, Jorge Soares, Joel Santos, Eduardo Ogasawara
 - Oct 20 2pm Gabriela Ruberg BCB
 - Oct 20 6pm High Performance Data Science Marta Mattoso, Alvaro Coutinho, Fabio Porto, Daniel Oliveira, Kary Ocana, Eduardo Ogasawara

October 18-22, 2021

Brazilian Symposium on Databases (SBBD)





SBBD 2021 – BRAZILIAN SYMPOSIUM ON DATABASES

The Premier Brazilian Conference on Data Science and Big Data

The annual **Brazilian Symposium on Databases (SBBD)** is the official event on databases of the Brazilian Computer Society (SBC). The symposium includes a technical program with research and industrial talks, tutorials, demos, and focused workshops. It also hosts invited talks by distinguished speakers from the international research community.

Due to COVID-19 and coronavirus pandemic, all activities of the 36th edition of the SBBD will happen online only, October 4-8, 2021 - organized by CEFET/RJ (Rio de Janeiro, Brazil).



TRACKS COORDINATION

Program Chair: Ricardo Torres (NTNU, Norway) Short Vision Industrial Chair: Damires Souza (IFPB, Brazil) Steering Committee Chair: Fabio Porto (LNCC, Brazil) Demos and Applications Chair: Leonardo Ribeiro (UFG, Brazil) Thesis and Dissertation Workshop Chair (WTDBD): Julio Reis (Unicamp, Brazil) CTDBD Chair: Cristina Ciferri (USP, Brazil) Short courses Chair: Alessandréia M de Oliveira (UFJF, Brazil) Tutorials Chair: Daniel de Oliveira (UFF, Brazil) Workshop Chair: Eduardo Almeida (UFPR, Brazil) WTAG Chair. André Carvalho (UFAM. Brazil)

ONLINE ORGANIZATION

SBBD General Chair.

Eduardo Ogawasara (CEFET/RJ) – eduardo.ogasawara@cefet-rj.br Rafaelli Coutinho (CEFET/RJ) – rafaelli.coutinho@cefet-rj.br

Data Analytics Lab



https://eic.cefet-rj.br/~dal/ http://dgp.cnpq.br/dgp/espelhogrupo/9806930220192669 https://www.youtube.com/channel/UCmn4Kh8fgI7VSM8X9t6gWmA

YouTube channel

P	esquisar			like
Eduardo 251 inscritos	Ogasawara			
INÍCIO VÍDEOS	PLAYLISTS CAI	NAIS DISCUSSÃO	SOBRE Q	
Envios que fazem sucesso	► REPRODUZIR TODOS			
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Tutorial do Hanafuda 1,8 mil visualizações • há 1 ano Playlists criadas	 Mineração de Dados - Introdução 490 visualizações • há 10 meses 	42:11 Introdução ao R - parte 1 312 visualizações • há 10 meses	Metodologia Científica - Introdução 204 visualizações * há 10 meses	
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Research Themes



Let's start

Time series

• A time series is a sequence of observations of a phenomenon of interest collected over time



• $y = \langle y_1, y_2, \dots, y_n \rangle, |y| = n$

Linear regression

- $y_t = \beta_0 + \beta_1 x_t + \omega_t$
- Capture linear trend
- x_t can also be a time variable

```
summary(fit <- lm(chicken~time(chicken), na.action=NULL))
# Estimate Std. Error t.value
# (Intercept) -7131.02 162.41 -43.91
# time(chicken) 3.59 0.08 44.43
# ...
# Residual standard error: 4.696 on 178 degrees of freedom
plot(chicken)
abline(fit)</pre>
```



R.H. Shumway and D.S. Stoffer, 2017, *Time Series Analysis and Its Applications: With R Examples*. Springer.
 R.J. Larsen and M.L. Marx, 2017, *An Introduction to Mathematical Statistics and Its Applications*. Pearson Education.
 D.N. Gujarati and D.C. Porter, 2008, *Basic Econometrics*. McGraw-Hill Publishing.

Polynomial regression

- $y_t = \beta_0 + \beta_1 x_t + \beta_2 x_t^2 + \dots + \beta_n x_t^n + \omega_t$
- Capture other degree components

```
x <- time(chicken)</pre>
x2 < - x^2
summary(fit2 <- lm(chicken~x+x2, na.action=NULL))</pre>
                   Estimate Std. Error t.value
#
     (Intercept)
                    -611100
                                   70560
                                             8.661
                                   70.25
                                            -8.711
                     -611.9
                Х
               x2
                     0.1532
                                             8.762
                                    0.02
   Residual standard error: 3.933 on 177 degrees of freedom
#
plot(chicken)
lines(fit2$fitted.values)
```



R.H. Shumway and D.S. Stoffer, 2017, *Time Series Analysis and Its Applications: With R Examples*. Springer.
 R.J. Larsen and M.L. Marx, 2017, *An Introduction to Mathematical Statistics and Its Applications*. Pearson Education.
 D.N. Gujarati and D.C. Porter, 2008, *Basic Econometrics*. McGraw-Hill Publishing.

Theory is important to support other degrees

```
> anova(fit, fit2)
Analysis of Variance Table
Model 1: chicken ~ x
Model 2: chicken \sim x + x^2
            RSS Df Sum of Sq
  Res.Df
                                     Pr(>F)
                                  F
     178 3925.9
1
     177 2738.2 1
                      1187.7 76.773 1.527e-15 ***
2
Signif. codes:
                  '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
                0
```



A detailed video explaining how to choose models is coming soon

Multiple regression problem

- $y_t = \beta_0 + \beta_1 x_{t1} + \beta_2 x_{t2} + \dots + \beta_n x_{tn} + \omega_t$
- $x_{t1}, x_{t2}, ..., x_{tn}$ are independent variables
 - They were commonly theoretically established
- ω_t is an intrinsic error, noise variable

Cardiovascular mortality in Los Angeles



[1] R.H. Shumway, A.S. Azari, and Y. Pawitan, 1988, Modeling mortality fluctuations in Los Angeles as functions of pollution and weather effects, *Environmental Research*, v. 45, n. 2 (Apr.), p. 224–241.

Model building

```
• Model 1: c_t = \beta_0 + \beta_1 t + \omega_t
```

```
• Model 2: c_t = \beta_0 + \beta_1 t + \beta_2 (te_t - \overline{te}) + \beta_3 (te_t - \overline{te})^2 + \beta_4 pa_t + \omega_t
```

```
temp = tempr-mean(tempr) # center temperature
temp2 = temp^2
trend = time(cmort) # time
fit = lm(cmort~ trend, na.action=NULL)
summary(fit)
summary(aov(fit))
fit2 = lm(cmort \sim trend + temp + temp2 + part, na.action=NULL)
summary(fit2)
summary(aov(fit2))
anova(fit, fit2)
> anova(fit, fit2)
Analysis of Variance Table
Model 1: cmort ~ trend
Model 2: cmort ~ trend + temp + temp2 + part
  Res.Df RSS Df Sum of Sq F Pr(>F)
1
     506 40020
```

503 20508 3 19511 159.52 < 2.2e-16 ***

2

```
> num = length(cmort) # sample size
> AIC(fit)/num - log(2*pi) # AIC
[1] 5.37846
> BIC(fit)/num - log(2*pi) # BIC
[1] 5.403443
> (AICc = log(sum(resid(fit)^2)/num)
+ + (num+5)/(num-5-2)) # AICc
[1] 5.390601
>
> num = length(cmort) # sample size
> AIC(fit2)/num - log(2*pi) # AIC
[1] 4.721732
> BIC(fit2)/num - log(2*pi) # BIC
[1] 4.771699
> (AICc = log(sum(resid(fit2)^2)/num)
+ + (num+5)/(num-5-2)) # AICC
[1] 4.722062
```

A detailed video explaining how to choose models is coming soon

[1] R.H. Shumway, A.S. Azari, and Y. Pawitan, 1988, Modeling mortality fluctuations in Los Angeles as functions of pollution and weather effects, *Environmental Research*, v. 45, n. 2 (Apr.), p. 224–241.

Regression with lagged values

- Independent variables can be lagged versions of y_t
 - $y_t = \beta_0 + \beta_1 y_{t-1} + \beta_2 y_{t-2} + \dots + \beta_n y_{t-n} + \omega_t$
 - ω_t is an intrinsic error, noise variable
- Open room for data-driven models

Autoregressive Integrated Moving Average

- ARIMA(p, d, q)
 - AR(p)

•
$$y_t = \phi_1 y_{t-1} + \phi_2 y_{t-2} + \dots + \phi_p y_{t-p} + \omega_t$$

MA (q)

•
$$y_t = \omega_t + \theta_1 \omega_{t-1} + \theta_2 \omega_{t-2} + \dots + \theta_n \omega_{t-q}$$

Differentiation (d)

A detailed video explaining AR and MA is coming soon

- Subsequence is a continuous sample of a time series
 - $seq_{p,i}(y) = \langle y_i, y_{i+1}, \dots, y_{i+p-1} \rangle$
 - $\left|seq_{p,i}(y)\right| = p$
 - 1 $\leq i \leq |y| p$
- Sliding window explores all subsequences of a time series
 - $sw_p(y) = A$
 - $\forall a_i \in A, a_i = seq_{p,i}(y)$



^	t4 [‡]	t3 [‡]	t2 [‡]	t1 [‡]	t0 [‡]
1	2.158484	2.312962	2.459529	2.594481	2.714406
2	2.312962	2.459529	2.594481	2.714406	2.816273
3	2.459529	2.594481	2.714406	2.816273	2.897507
4	2.594481	2.714406	2.816273	2.897507	2.956056
5	2.714406	2.816273	2.897507	2.956056	2.990438
6	2.816273	2.897507	2.956056	2.990438	2.999785

Sliding window of size 5

[1] H. Borges, M. Dutra, A. Bazaz, R. Coutinho, F. Perosi, F. Porto, F. Masseglia, E. Pacitti, and E. Ogasawara, 2020, Spatial-time motifs discovery, *Intelligent Data Analysis*, v. 24, n. 5, p. 1121–1140.

Prediction using sliding windows (lagged terms) Mining process



[1] R. Salles, L. Assis, G. Guedes, E. Bezerra, F. Porto, and E. Ogasawara, 2017, A framework for benchmarking machine learning methods using linear models for univariate time series prediction, In: *Proceedings of the International Joint Conference on Neural Networks*, p. 2338–2345

Nonstationarity

Time series

- Statistical properties may vary over time
 - $\chi(\hat{y}_s) \neq \chi(\hat{y}_t)$



0 2

8

10

4 6

х

Stationarity

- Stationarity
 - Time series y
 - Samples \hat{y}_s from y
 - Statistical properties in \hat{y}_{s} do not vary over time
 - Mean $\mu(\hat{y}_s) \cong \mu(\hat{y}_t)$
 - Variance: $\sigma^2(\hat{y}_s) \cong \sigma^2(\hat{y}_t)$
 - Covariance: $cov(\hat{y}_s, \hat{y}_{s+d}) \cong cov(\hat{y}_t, \hat{y}_{t+d})$
- Non-stationarity
 - When stationary does not hold

Stationarity and non-stationary time series



Most data analytics methods implicitly assume stationarity



Possible solutions

- Assumption of stationarity
- Adaptability
 - Drift detection
 - Memory management
- Transformation methods

Assumption of stationarity



Adaptability

- Some machine learning methods (e.g., neural networks) are known for adaptability
 - Ability to update model due to changes in the environment
 - Incremental training
- Adaptive systems aim to address non-stationarity
 - Seeking robustness, adaptability is adopted
 - Greater adaptability, more susceptible to spurious situations, less robust
 - Dilemma: finding the right time to adapt



[1] S.O. Haykin, 2008, Neural Networks and Learning Machines. 3 ed. New York, Prentice Hall.

[2] Grossberg, S., 1988. Neural Networks and Natural Intelligence, Cambridge, MA: MIT Press.

[3] G. Ditzler, M. Roveri, C. Alippi, e R. Polikar, 2015, Learning in Nonstationary Environments: A Survey, IEEE Computational Intelligence Magazine, v. 10, n. 4, p. 12–25.

Drift detection

- Drift detection
 - Active
 - Passive
- Learning
 - Incremental
 - Non-incremental
- Models
 - Single
 - Ensemble (Boosting)



[1] J. Gama, I. Zliobaite, A. Bifet, M. Pechenizkiy, e A. Bouchachia, 2014, A survey on concept drift adaptation, ACM Computing Surveys, v. 46, n. 4 [2] A.M. García-Vico, C.J. Carmona, D. Martín, M. García-Borroto, e M.J. del Jesus, 2018, An overview of emerging pattern mining in supervised descriptive rule discovery: taxonomy, empirical study, trends, and prospects, Wiley Interdisciplinary Reviews: Data Mining and Knowledge Discovery, v. 8, n. 1 [3] G.I. Webb, R. Hyde, H. Cao, H.L. Nguyen, e F. Petitjean, 2016, Characterizing concept drift, Data Mining and Knowledge Discovery, v. 30, n. 4, p. 964–994.

Lucas critique

 "Given that the structure of an econometric model consists of optimal decision rules of economic agents, and that optimal decision rules vary systematically with changes in the structure of series relevant to the decision maker, it follows that any change in policy will systematically alter the structure of econometric models."

Goes toward memory management

Memory management

- Process
 - It is tested in the last batch (forecast)
 - The last batch is incorporated in the training
- Memory
 - complete
 - Without memory
 - sliding windows



[1] J. Gama, I. Zliobaite, A. Bifet, M. Pechenizkiy, e A. Bouchachia, 2014, A survey on concept drift adaptation, ACM Computing Surveys, v. 46, n. 4

[2] A.M. García-Vico, C.J. Carmona, D. Martín, M. García-Borroto, e M.J. del Jesus, 2018, An overview of emerging pattern mining in supervised descriptive rule discovery: taxonomy, empirical 31 study, trends, and prospects, Wiley Interdisciplinary Reviews: Data Mining and Knowledge Discovery, v. 8, n. 1

Transformation methods



A detailed video explaining transformations is coming soon

32

Detrending and differentiation

- Detrending
 - $\hat{y}_t = y_t (\beta_0 + \beta_1 x_t)$
- Differentiation (d)
 - First order differentiation (d = 1)
 - $\hat{y}_t = \nabla y_t = y_t y_{t-1}$
 - General order differentiation (d > 1)

•
$$\nabla^d = (1 - B)^d$$
, $B^k y_t = y_{t-k}$



A detailed video explaining detrending and differentiation is coming soon

Normalization issues using sliding windows



Adaptive Normalization

- Transformation
 - Using sliding windows
 - Compute moving average (inertia)
 - Remove inertia
 - Outlier removal
 - Sliding window min-max
- Inverse transform
 - Prediction
 - Denormalization
 - Add inertia

A detailed video explaining AN is coming soon

Intuition



A detailed video explaining AN is coming soon

[1] E. Ogasawara, L.C. Martinez, D. De Oliveira, G. Zimbrão, G.L. Pappa, and M. Mattoso, 2010, Adaptive Normalization: A novel data normalization approach for nonstationary time series, In: *Proceedings of the International Joint Conference on Neural Networks*

Different preprocessing and prediction methods



Road map

Next videos

- Linear model fitting
- Linear model selection
- Trends and Differentiation
- Seasonal Adjustment
- Spectral Analysis
- Smoothing and Filtering
- Autocorrelation
- ARIMA
- GARCH
- State Space Models

- Sliding windows and normalization
- Adaptive normalization
- Machine learning models
- Data sampling
- Mining process
- Performance evaluation
 - evaluation on a rolling forecasting origin (time series cross validation)

https://www.youtube.com/channel/UCAm1hAXWEqYJfXz4EzzBhVg

[1] R.J. Hyndman and G. Athanasopoulos, 2018, Forecasting: principles and practice. OTexts.

[2] R.H. Shumway and D.S. Stoffer, 2017, Time Series Analysis and Its Applications: With R Examples. Springer.

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