

Caminhos Cruzados Entre Visão Computacional e Visão Biológica

Ricardo Marroquim

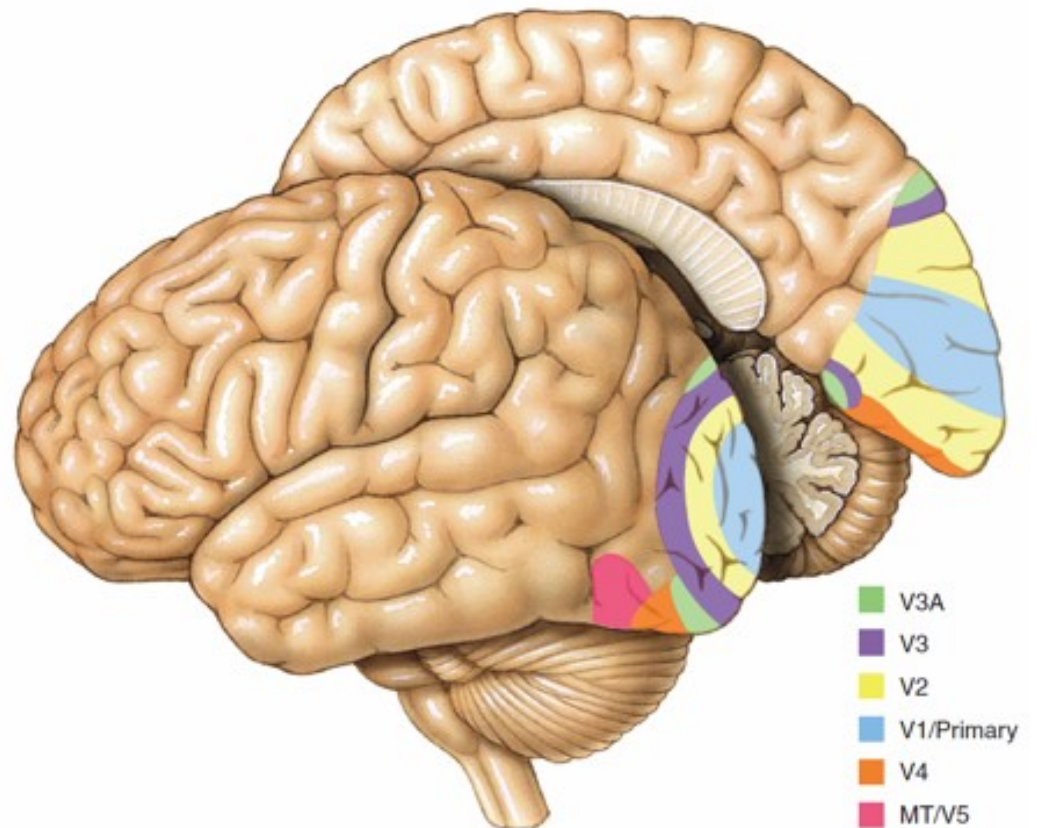
www.lcg.ufrj.br/marroquim



Laboratório de
Computação
Gráfica



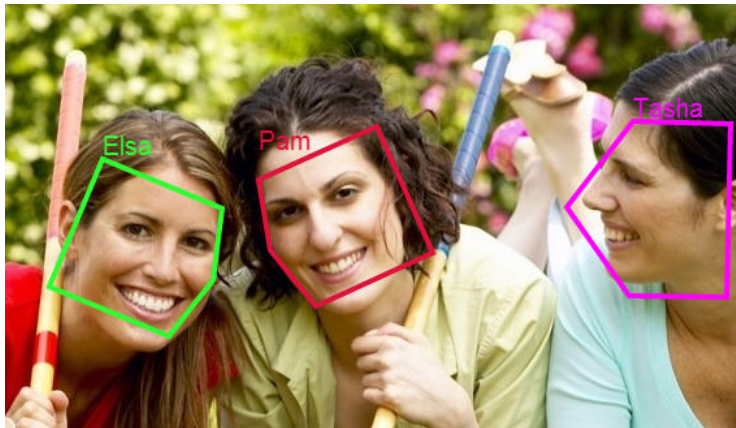
how do we see?



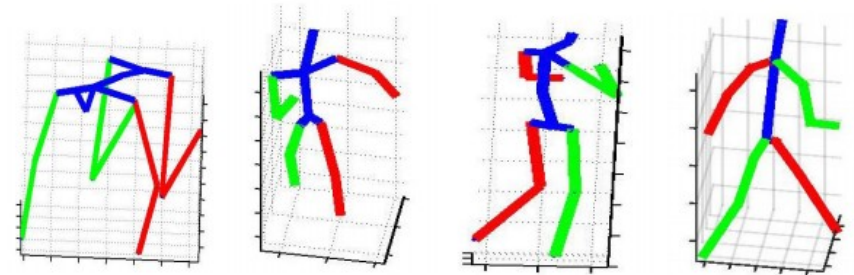
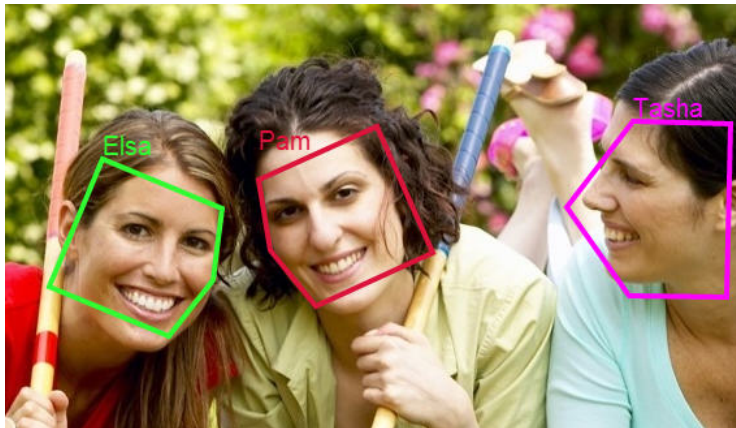
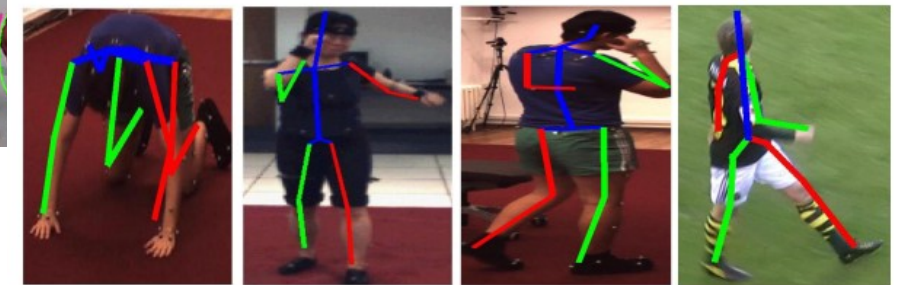
how computers see?



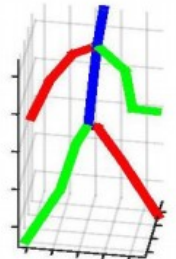
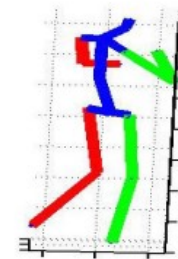
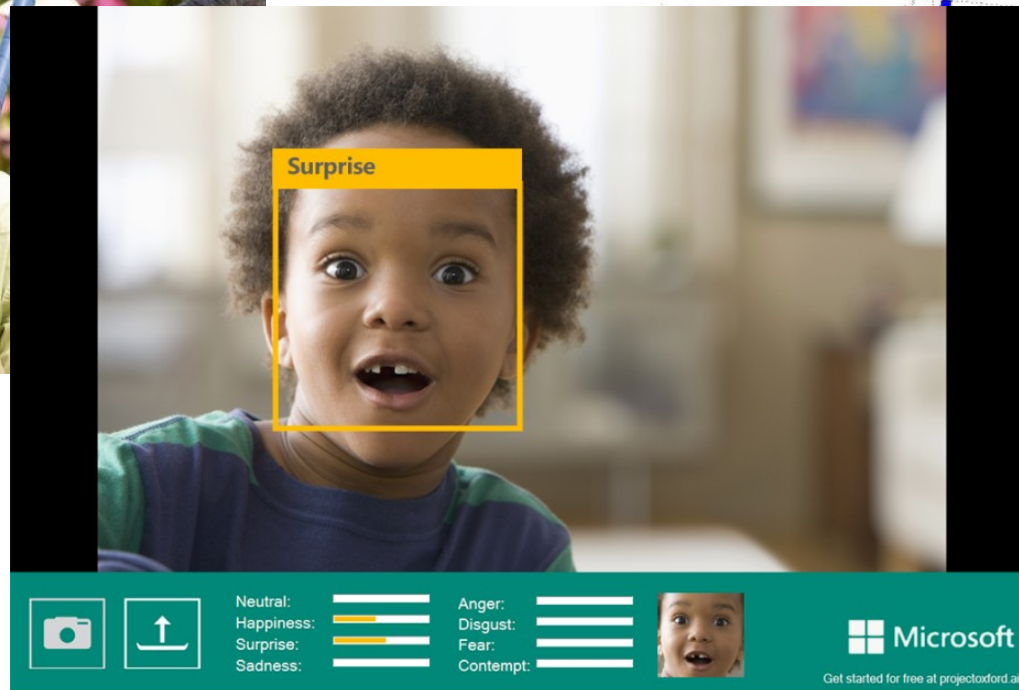
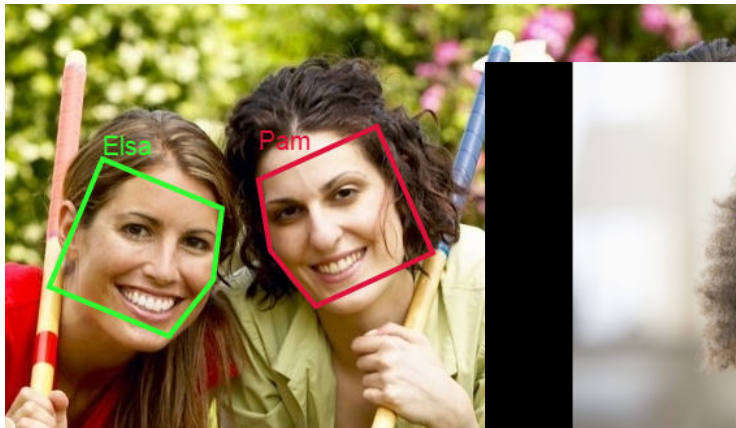
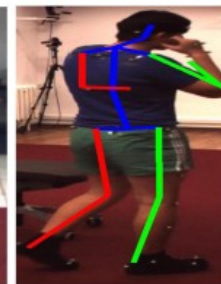
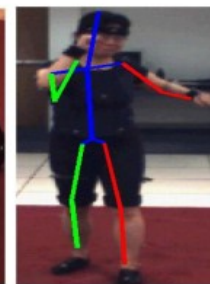
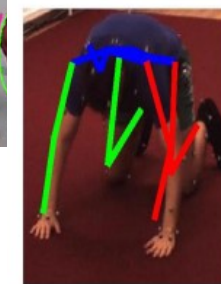
computer vision



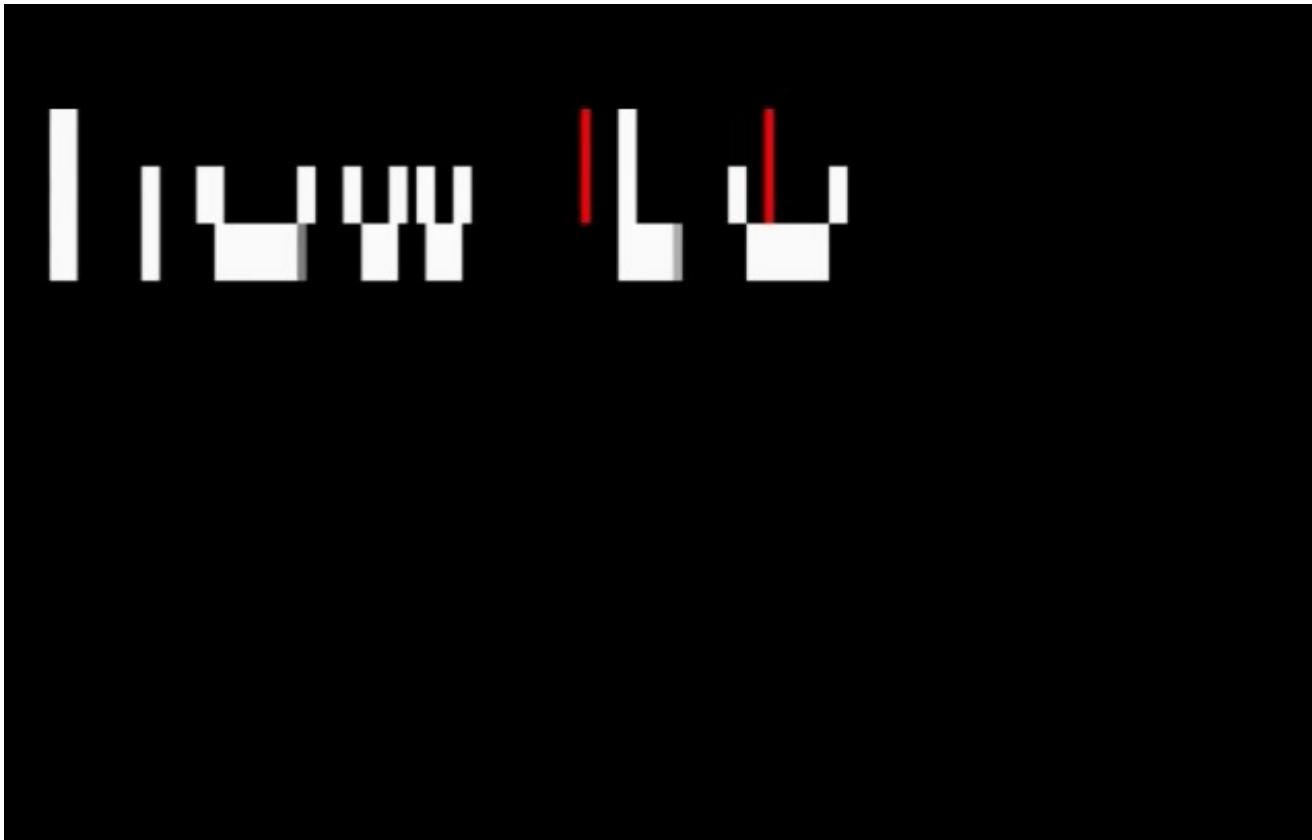
computer vision



computer vision

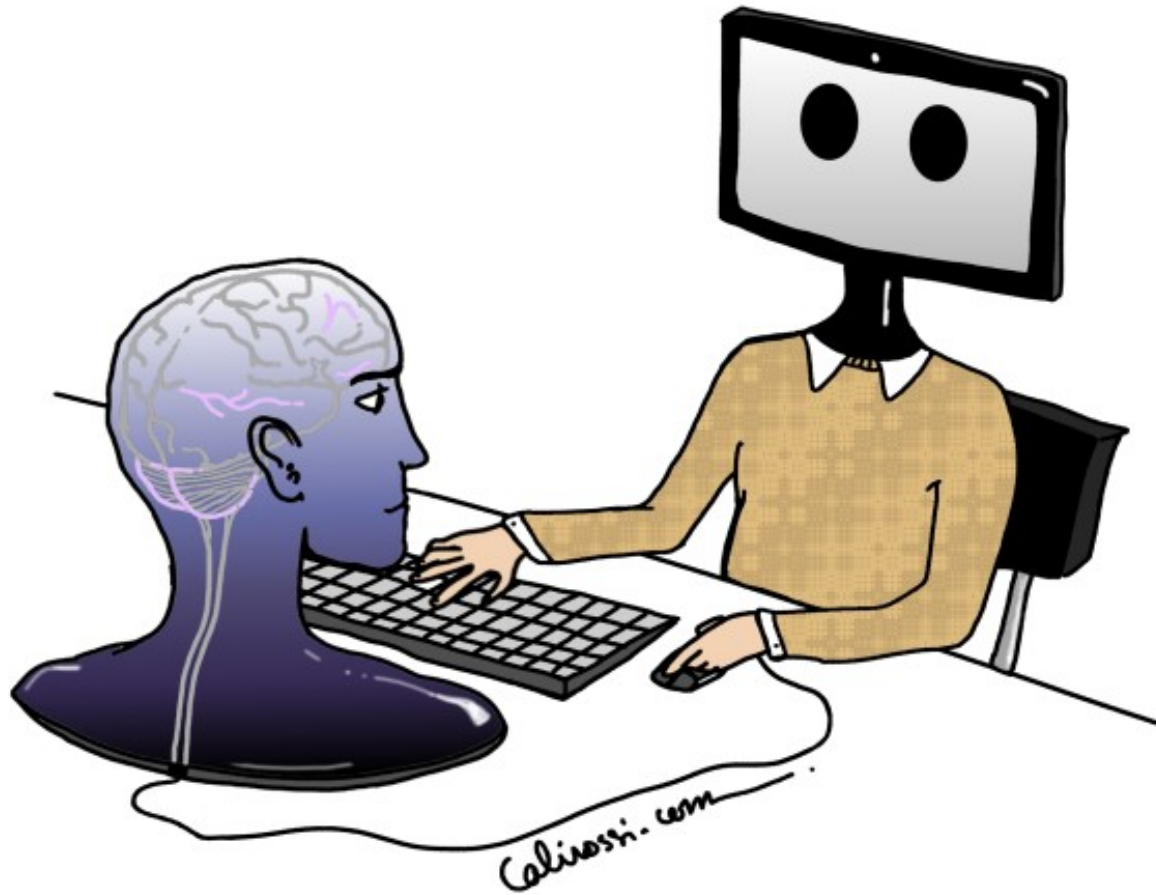


computer vision



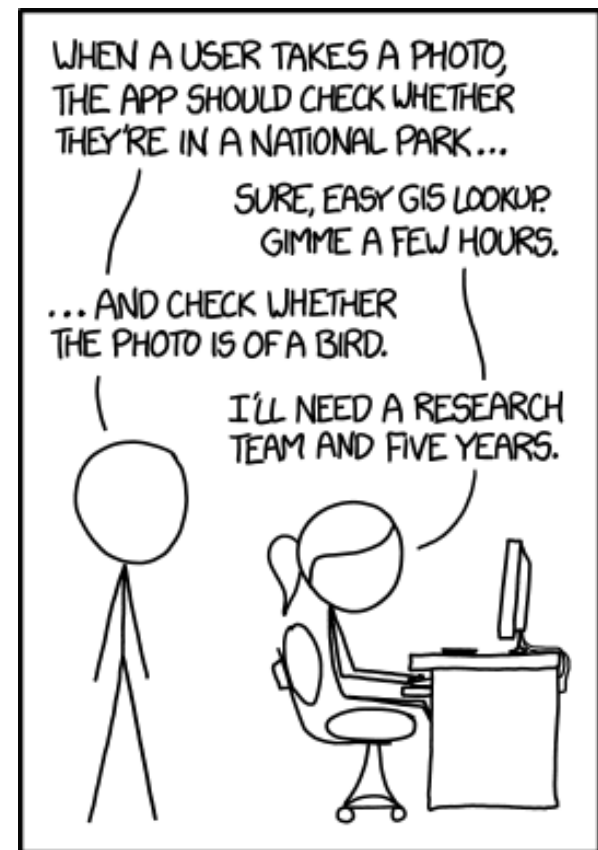
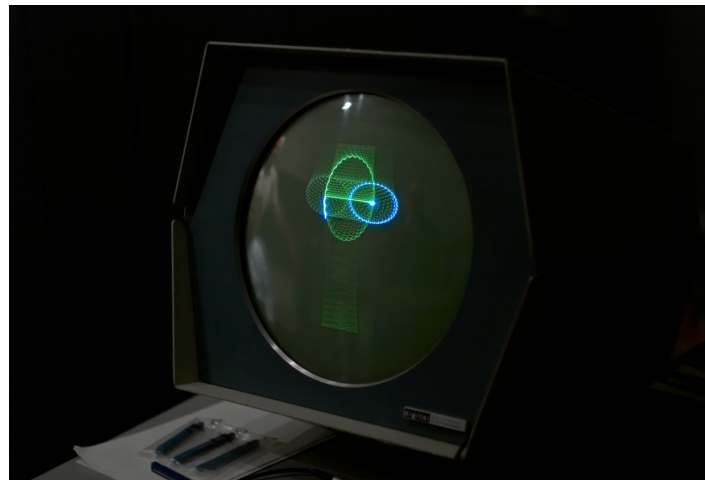
<https://www.youtube.com/watch?v=eQLcDmfmGB0>

humans vs computers



Marvin Minsky

- pioneer: Perceptrons, Logo turtle, Head-mounted display ...
- 1969: Turing Award



IN CS, IT CAN BE HARD TO EXPLAIN THE DIFFERENCE BETWEEN THE EASY AND THE VIRTUALLY IMPOSSIBLE.

Larry Roberts

- 1963 - PhD Thesis: Machine Perception of Three-Dimensional Solids

MACHINE PERCEPTION OF THREE-DIMENSIONAL SOLIDS

by

LAWRENCE GILMAN ROBERTS

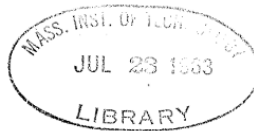
S.B., Massachusetts Institute of Technology
(1961)

M.S., Massachusetts Institute of Technology
(1961)

SUBMITTED IN PARTIAL FULFILLMENT OF THE
REQUIREMENTS FOR THE DEGREE OF
DOCTOR OF PHILOSOPHY

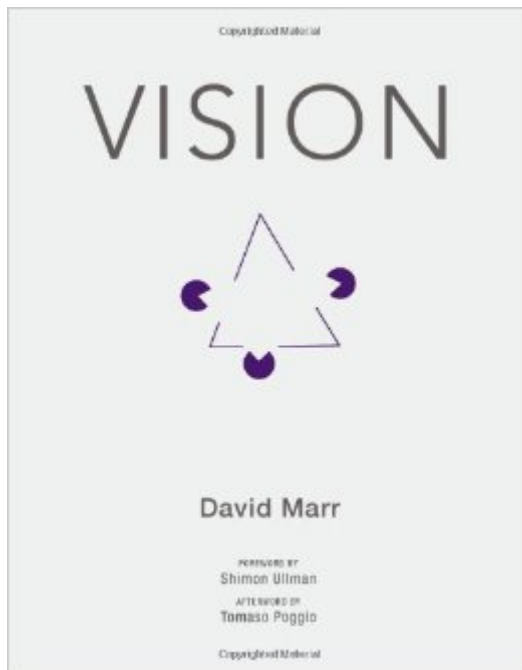
at the

MASSACHUSETTS INSTITUTE OF TECHNOLOGY
June, 1963

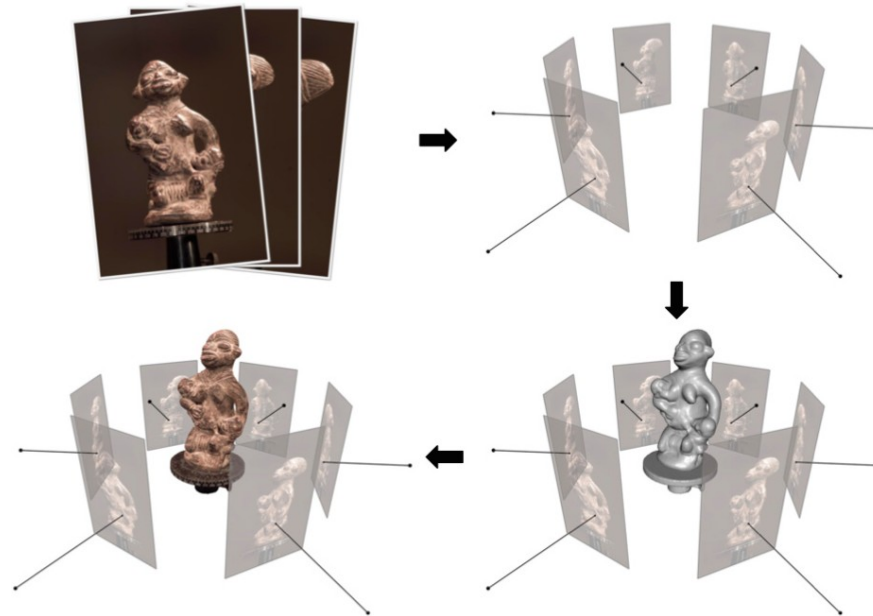


David Marr

- 1982 - David Marr - Vision: A Computational Investigation into the Human Representation and Processing of Visual Information



computer vision



Classification



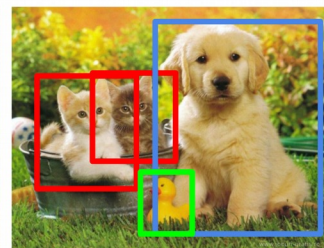
CAT

**Classification
+ Localization**



CAT

Object Detection



CAT, DOG, DUCK

**Instance
Segmentation**



CAT, DOG, DUCK

Single object

Multiple objects

projective geometry

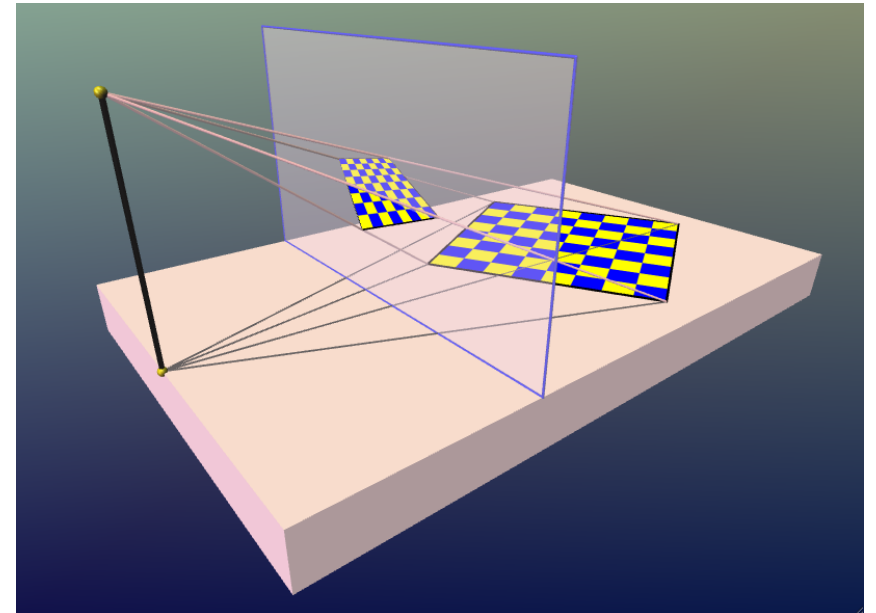
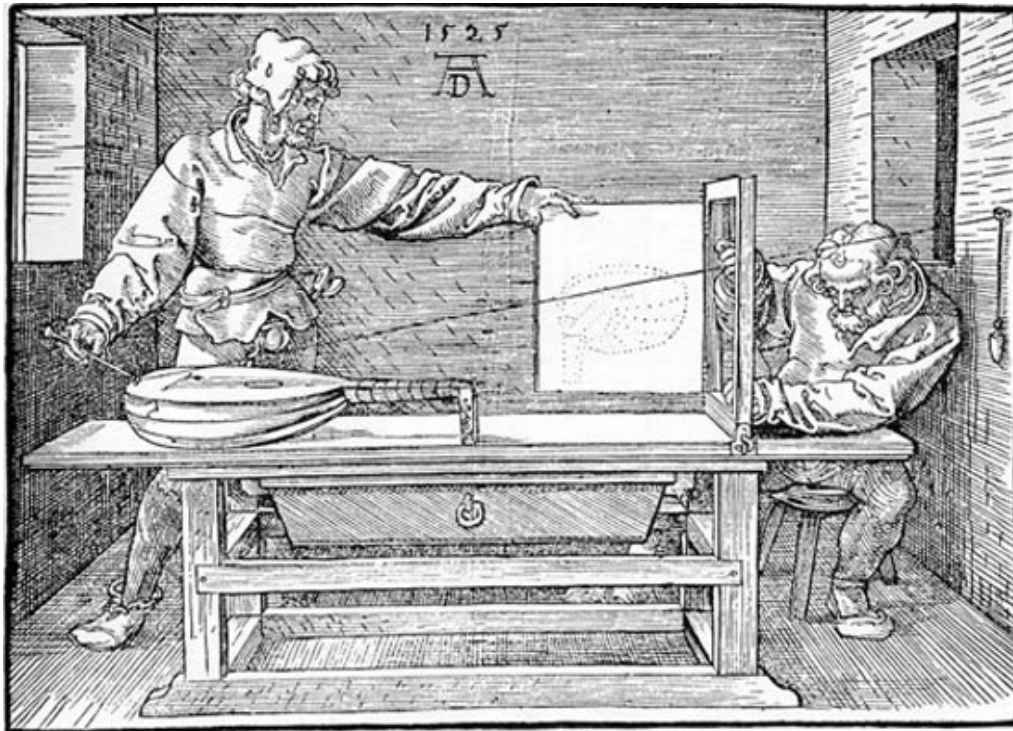
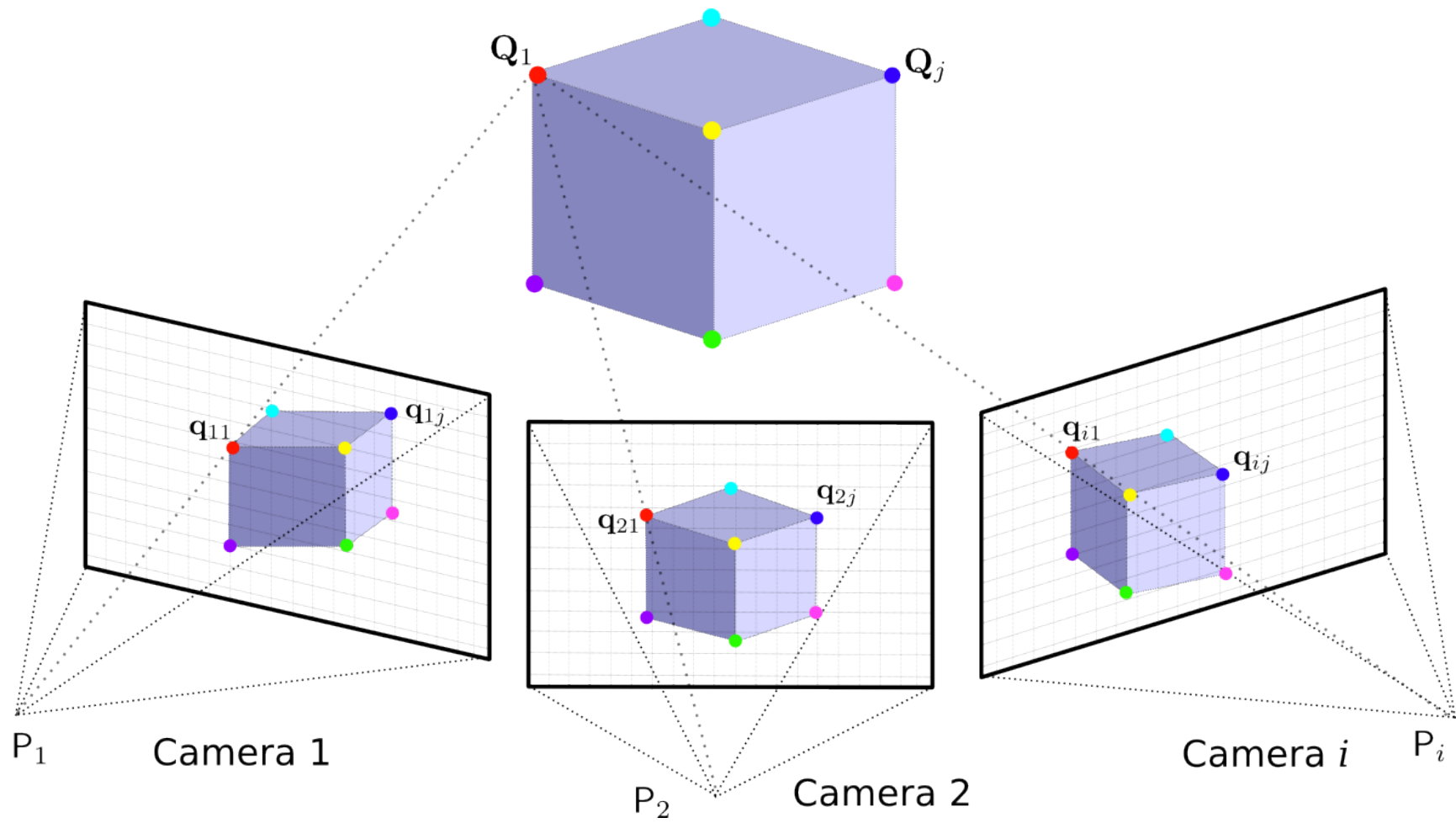


photo pop-up



<http://dhoiem.cs.illinois.edu/projects/popup/>

projective geometry



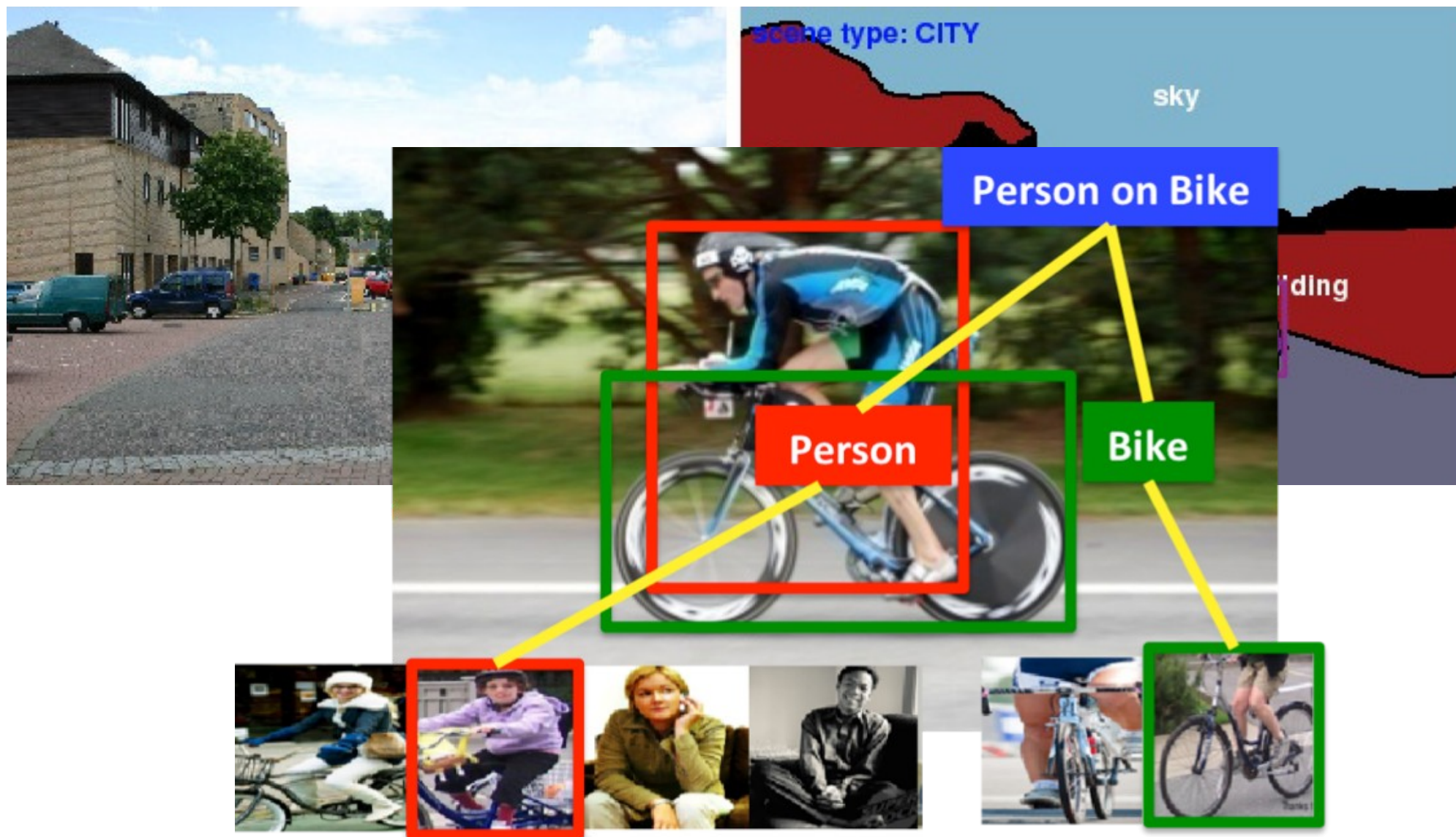
3D reconstruction



understanding



understanding



understanding

OPEN ACCESS Freely available online

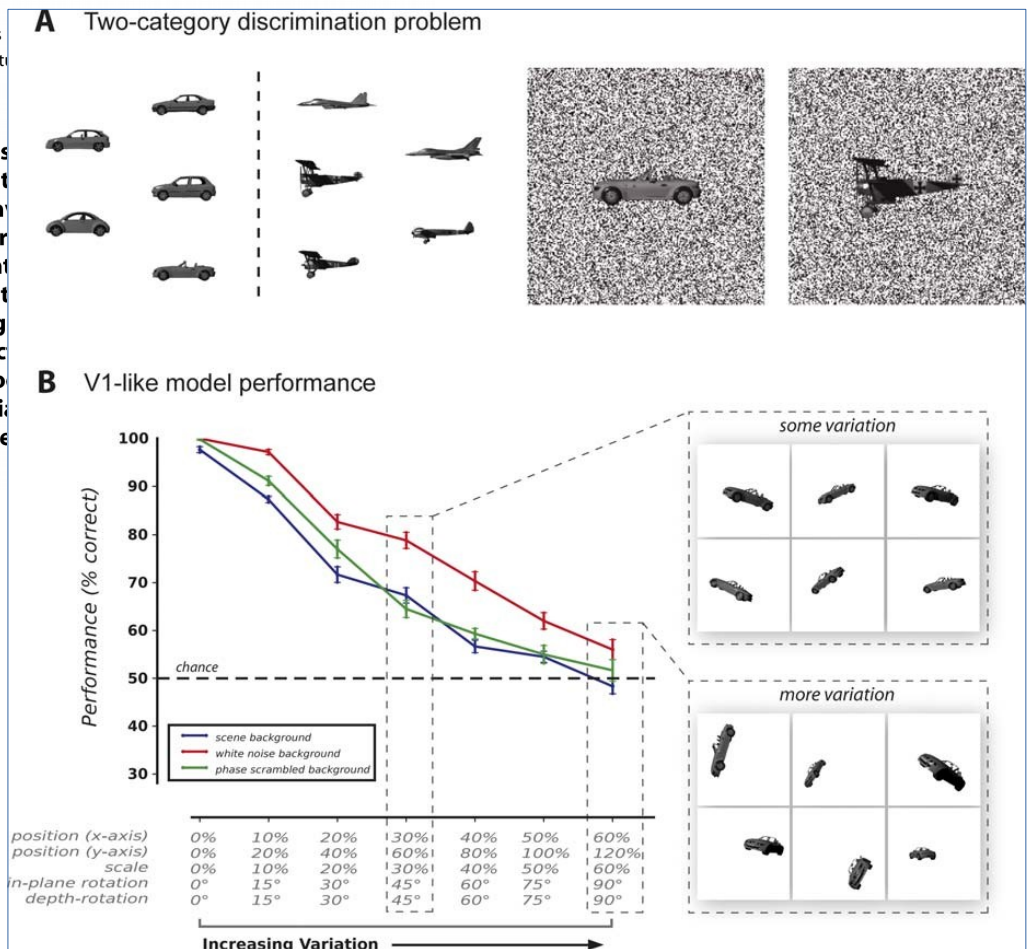
PLOS COMPUTATIONAL BIOLOGY

Why is Real-World Visual Object Recognition Hard?

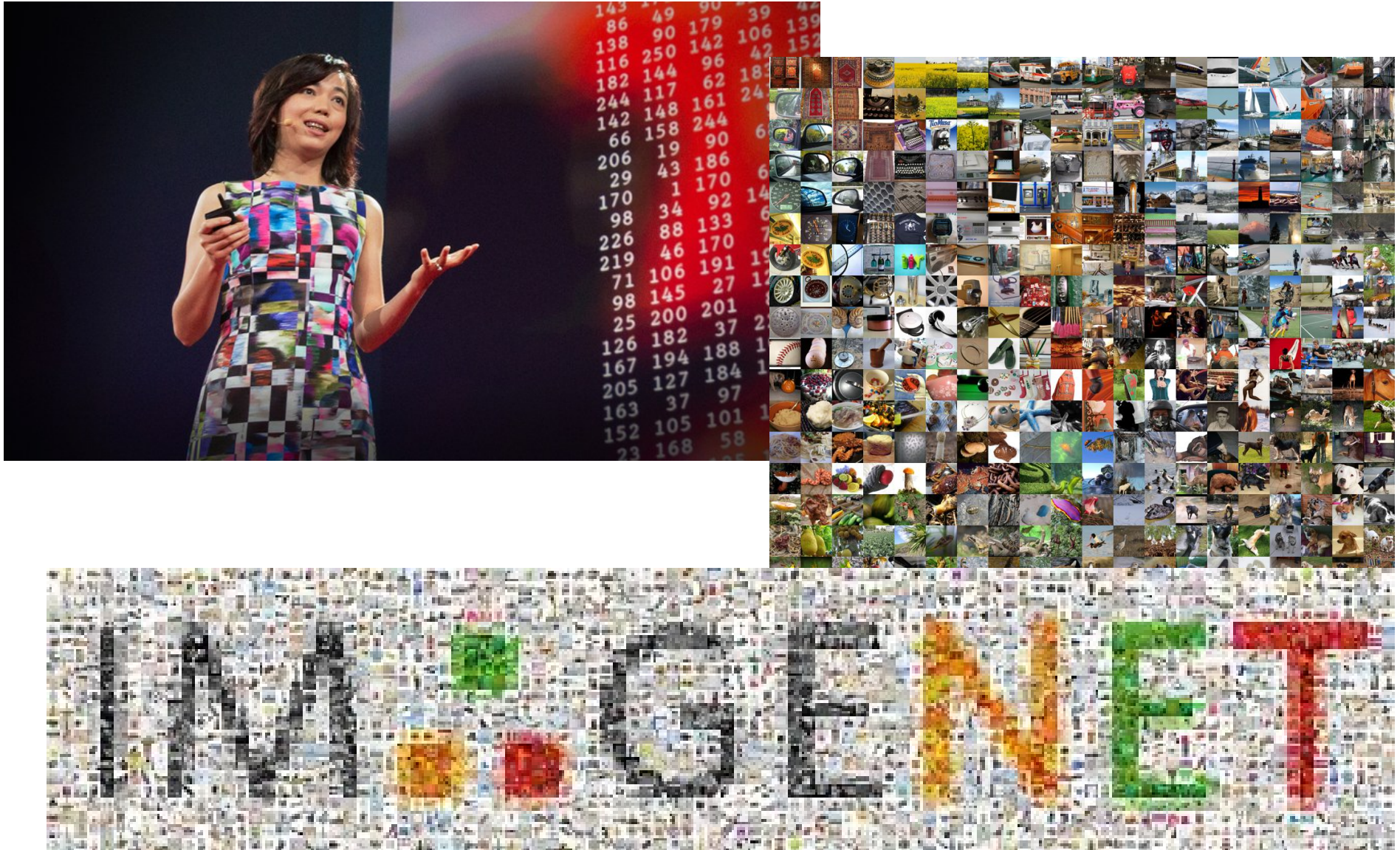
Nicolas Pinto^{1,2}, David D. Cox^{1,2,3}, James J. DiCarlo^{1,2*}

1 McGovern Institute for Brain Research, Massachusetts Institute of Technology, Cambridge, Massachusetts, United States
2 Department of Brain and Cognitive Sciences, Massachusetts Institute of Technology, Cambridge, Massachusetts, United States of America, **3** The Rowland Institute for Science, Cambridge, Massachusetts, United States of America

Progress in understanding the brain mechanisms underlying vision requires the construction of models that not only emulate the brain's anatomy and physiology, but ultimately match its performance. In recent years, “natural” images have become popular in the study of vision and have led to impressive progress in building such models. Here, we challenge the use of uncontrolled natural images in that progress. In particular, we show that a simple V1-like model—a neuroscience-inspired model—performs poorly at real-world visual object recognition tasks—outperforms state-of-the-art models (biologically inspired and otherwise) on a standard, ostensibly natural image recognition task. We designed a “simpler” recognition test to better span the real-world variation in object recognition. We show that this test correctly exposes the inadequacy of the V1-like model. Taken together, our results show that tests based on uncontrolled natural images can be seriously misleading, potentially leading to incorrect conclusions in the wrong direction. Instead, we reexamine what it means for images to be natural and argue that the fundamental problem of object recognition—real-world image variation.



Fei Fei Li



https://www.ted.com/talks/fei_fei_li_how_we_re_teaching_computers_to_understand_picture

deep learning

ImageNet Classification with Deep Convolutional Neural Networks

Alex Krizhevsky

University of Toronto

kriz@cs.utoronto.ca

Ilya Sutskever

University of Toronto

ilya@cs.utoronto.ca

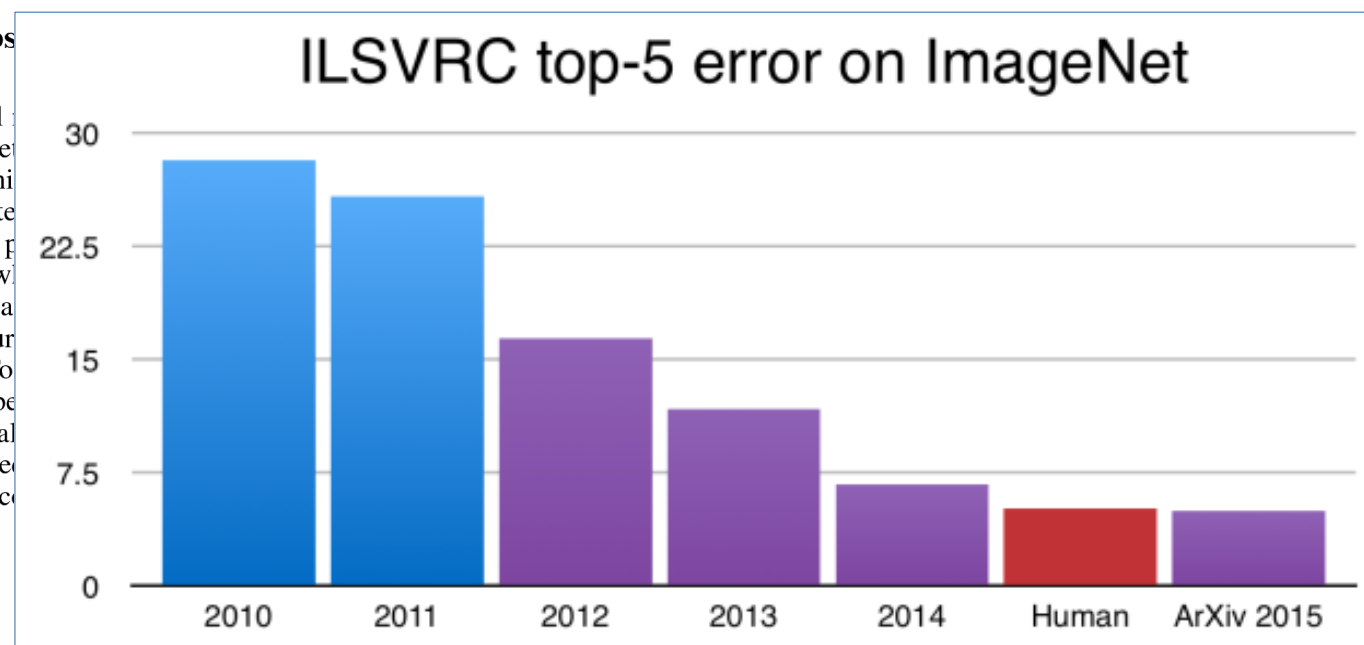
Geoffrey E. Hinton

University of Toronto

hinton@cs.utoronto.ca

Abs

We trained a large, deep convolutional neural network on high-resolution images in the ImageNet dataset. On the test data, we achieved an error rate of 17.0% which is considerably better than the previous state-of-the-art. Our network has 60 million parameters and consists of five convolutional layers, some of which have over 48 filters. In addition, we used a recently-developed technique for computing gradients of the convolution operation, which allowed us to train the network faster. To further reduce error, we employed a recently-developed technique for data augmentation that proved to be very effective. We achieved a top-5 error rate of 4.8% on the ILSVRC-2012 competition and achieved a top-1 error rate of 1.6% compared to 26.2% achieved by the second-place team.



deep learning

DenseCap: Fully Convolutional Localization Networks for Dense Captioning

Justin Johnson* Andrej Karpathy* Li Fei-Fei
Department of Computer Science, Stanford University
{jcsjohns, karpathy, feifeili}@cs.stanford.edu

Abstract

We introduce the dense captioning task, which requires a computer vision system to both localize and describe salient regions in images in natural language. The dense captioning task generalizes object detection when the descriptions consist of a single word, and Image Captioning when one predicted region covers the full image. To address the localization and description task jointly we propose a Fully Convolutional Localization Network (FCLN) architecture that processes an image with a single, efficient forward pass, requires no external regions proposals, and can be trained end-to-end with a single round of optimization. The architecture is composed of a Convolutional Network, a novel

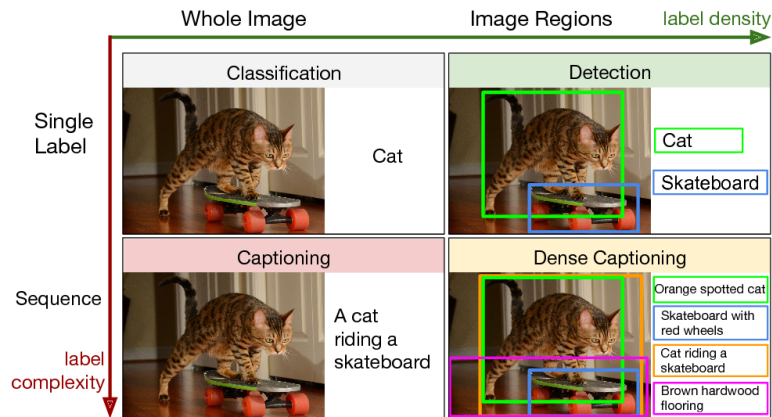


Figure 1. We address the Dense Captioning task (bottom right) with a model that jointly generates both dense and rich annotations in a single forward pass.

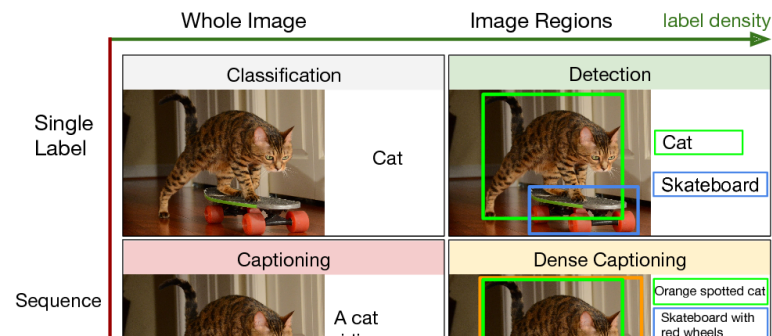
deep learning

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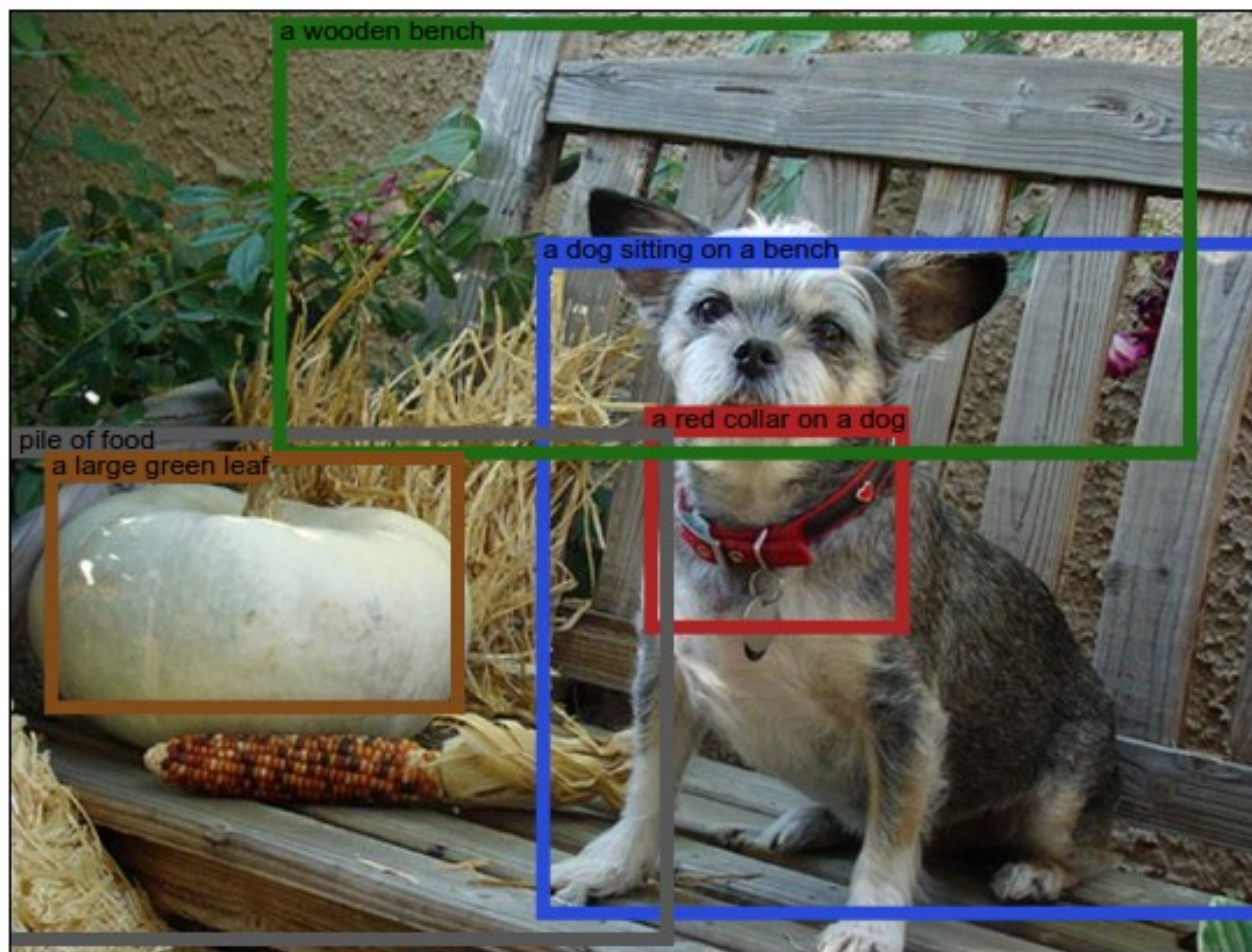
deep learning

DenseCap: Fully

Abs

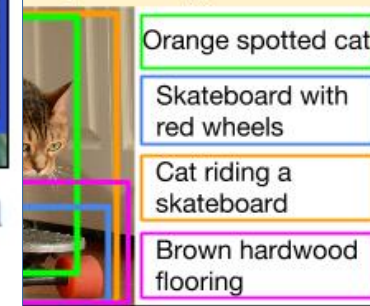
We introduce the dense captioning computer vision system to both classification and captioning tasks. The system generalizes object detection, where each predicted region covers the full image, to captioning, where each predicted region covers the full image.

Classification



a red collar on a dog. a dog sitting on a bench. a pile of food. a wooden bench. a large green leaf.

Captioning



ACM Prize in Computing

What Makes Paris Look like Paris?

Carl Doersch¹ Saurabh Singh¹ Abhinav Gupta¹ Josef Sivic² Alexei A. Efros^{1,2}
¹Carnegie Mellon University ²INRIA / Ecole Normale Supérieure, Paris



Figure 1: These two photos might seem nondescript, but each contains hints about which city it might belong to. Given a large image database of a given city, our algorithm is able to automatically discover the geographically-informative elements (patch clusters to the right of each photo) that help in capturing its “look and feel”. On the left, the emblematic street sign, a balustrade window, and the balcony support are all very indicative of Paris, while on the right, the neoclassical columned entryway sporting a balcony, a Victorian window, and, of course, the cast iron railing are very much features of London.



Abstract

Given a large repository of geotagged imagery, we seek to automatically find visual elements, e.g. windows, balconies, and street

1 Introduction

Consider the two photographs in Figure 1, both downloaded from Google Street View. One comes from Paris, the other one from



and balconies, and street signs, among representative elements at different geo-spatial scales, and geographically-informed image retrieval.

windows with railings, the particular style of balconies, the distinctive doorways, the traditional blue/green/white street signs, etc. were particularly helpful. Finding those features can be difficult

Scene Completion Using Millions of Photographs

James Hays Alexei A. Efros
Carnegie Mellon University

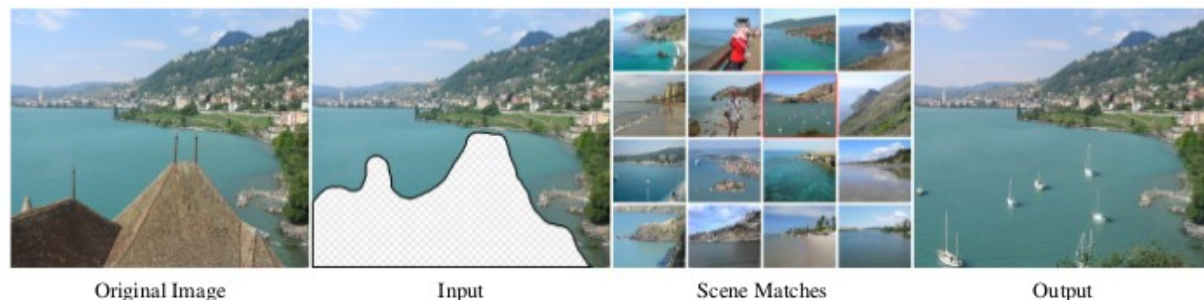


Figure 1: Given an input image with a missing region, we use matching scenes from a large collection of photographs to complete the image.

Abstract

What can you do with a million images? In this paper we present a new image completion algorithm powered by a huge database of photographs gathered from the Web. The algorithm patches up holes in images by finding similar image regions in the database that are not only seamless but also semantically valid. Our chief insight is that while the space of images is effectively infinite, the space of semantically differentiable scenes is actually not that large. For many image completion tasks we are able to find similar scenes which contain image fragments that will convincingly complete the image. Our algorithm is entirely data-driven, requiring no annotations or labelling by the user. Unlike existing image completion methods, our algorithm can generate a diverse set of results for each input image and we allow users to select among them. We demonstrate the superiority of our algorithm over existing image completion approaches.

Keywords: Image Completion. Image Database. Image Com-

pletion. There are two fundamentally different strategies for image completion. The first aims to reconstruct, as accurately as possible, the data that *should have been* there, but somehow got occluded or corrupted. Methods attempting an accurate reconstruction have to use some other source of data in addition to the input image, such as video (using various background stabilization techniques, e.g. [Irani et al. 1995]) or multiple photographs of the same physical scene [Agarwala et al. 2004; Snavely et al. 2006].

The alternative is to try finding a plausible way to fill in the missing pixels, hallucinating data that *could have been* there. This is a much less easily quantifiable endeavor, relying instead on the studies of human visual perception. The most successful existing methods [Criminisi et al. 2003; Drori et al. 2003; Wexler et al. 2004; Wilczkowiak et al. 2005; Komodakis 2006] operate by extending adjacent textures and contours into the unknown region. This idea is derived from example-based texture synthesis [Efros and Leung 1999; Efros and Freeman 2001; Kwatra et al. 2003; Kwatra et al. 2005].

Scene Completion Using Millions of Photographs

James Hays

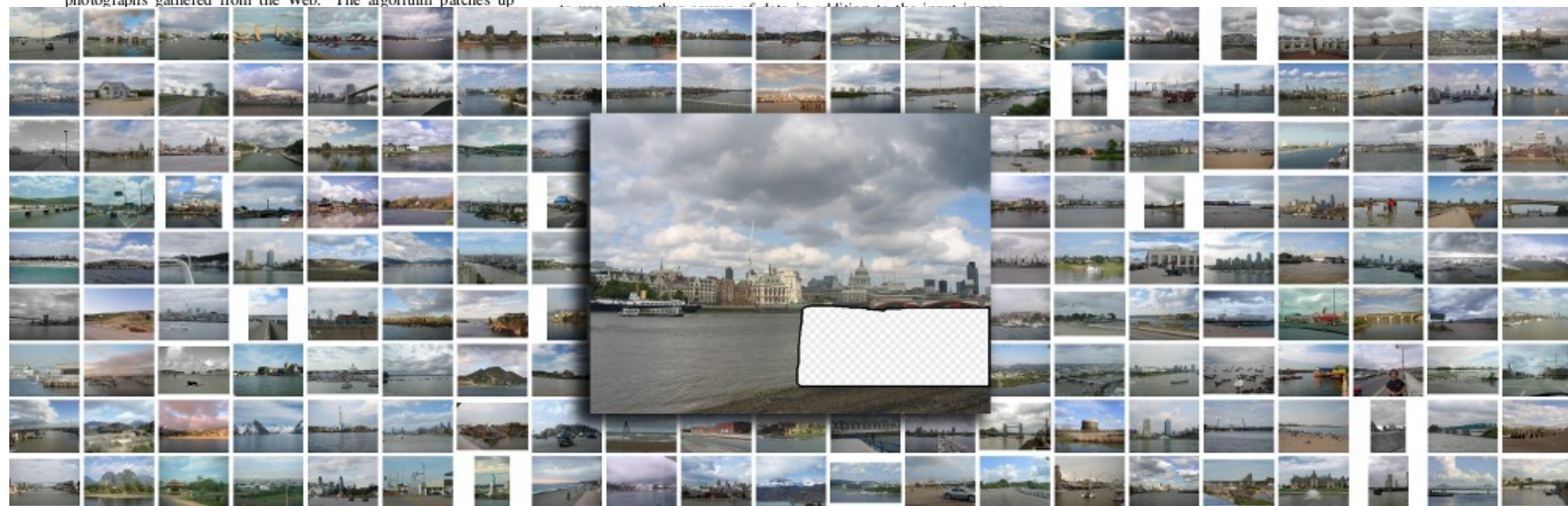
Alexei A. Efros

Carnegie Mellon University



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Colorful Image Colorization

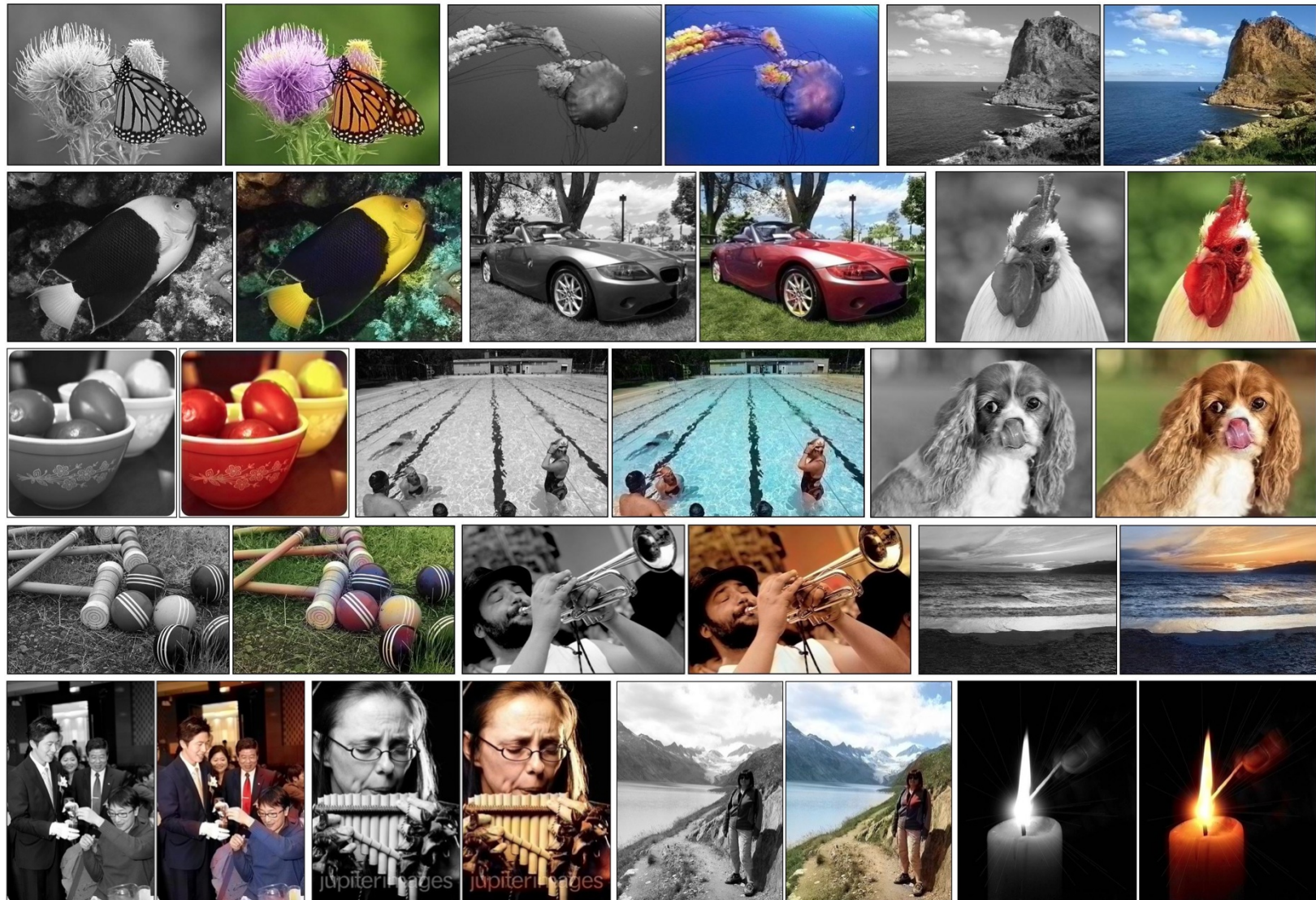
Richard Zhang, Phillip Isola, Alexei A. Efros
{rich.zhang,isola,efros}@eecs.berkeley.edu

University of California, Berkeley

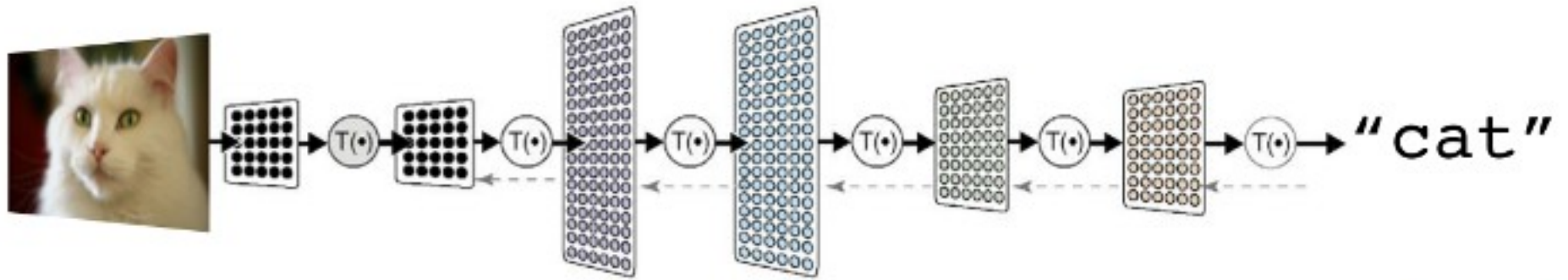
Abstract. Given a grayscale photograph as input, this paper attacks the problem of hallucinating a *plausible* color version of the photograph. This problem is clearly underconstrained, previous approaches have either relied on significant user interaction or resulted in desaturated colorizations. We propose a fully automatic approach that produces vibrant and realistic colorizations. We embrace the underlying uncertainty of the problem by posing it as a classification task and use class-rebalancing at training time to increase the diversity of colors in the result. The system is implemented as a feed-forward pass in a CNN at test time and is trained on over a million color images. We evaluate our algorithm using a “colorization Turing test,” asking human participants to choose between a generated and ground truth color image. Our method successfully fools humans on 32% of the trials, significantly higher than previous methods. Moreover, we show that colorization can be a powerful pretext task for

Colorful Image Colorization

Richard Zhang, Phillip Isola, Alexei A. Efros

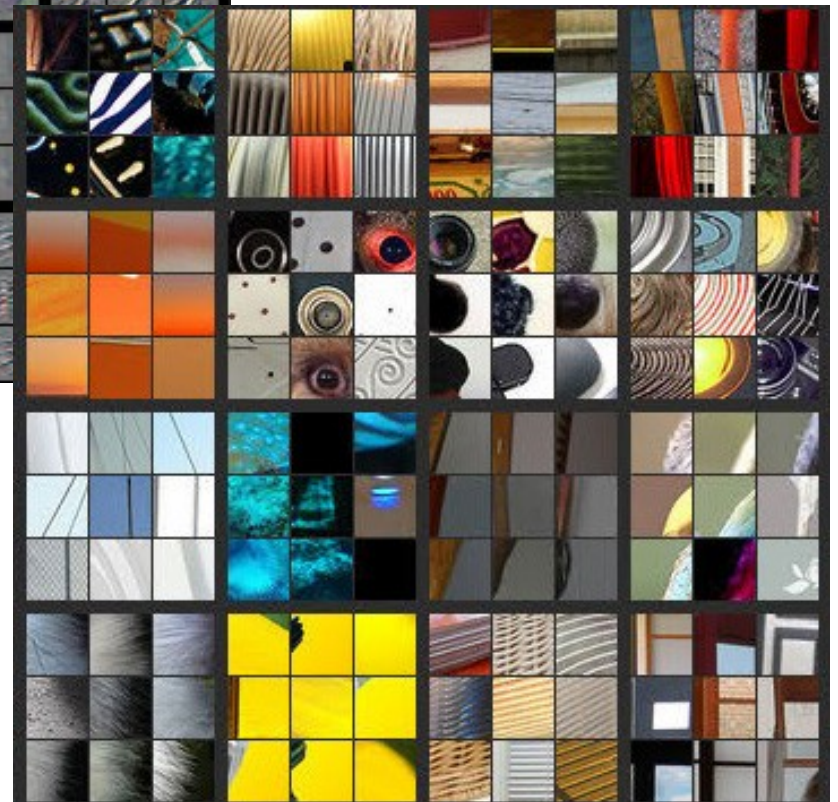
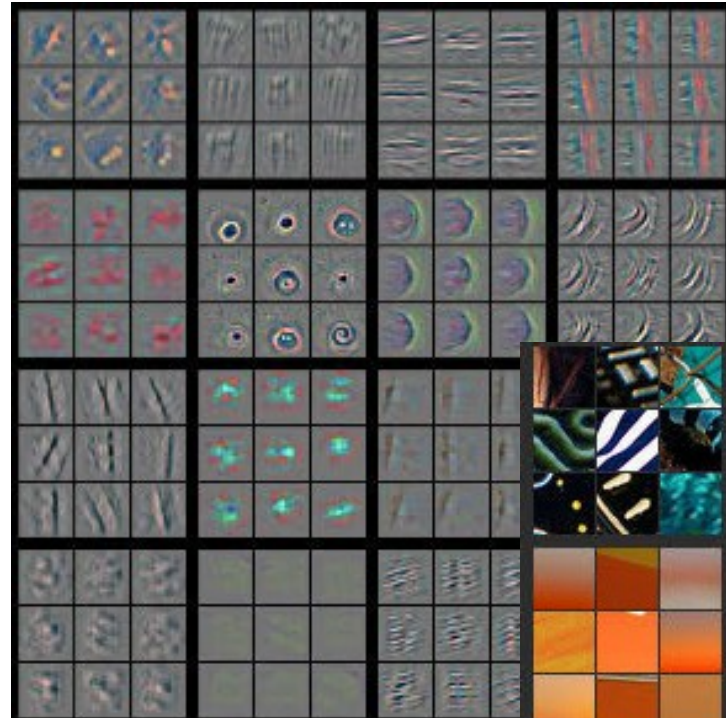
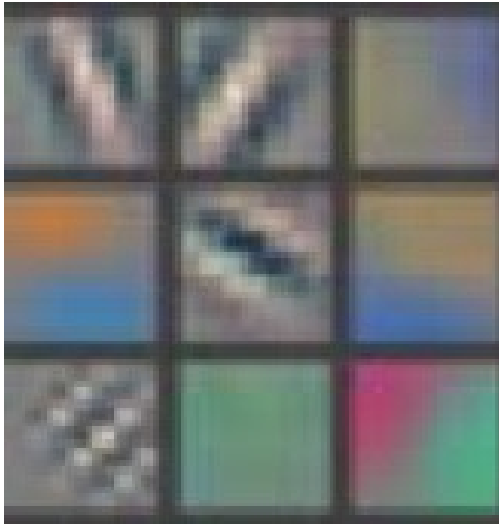


deep learning

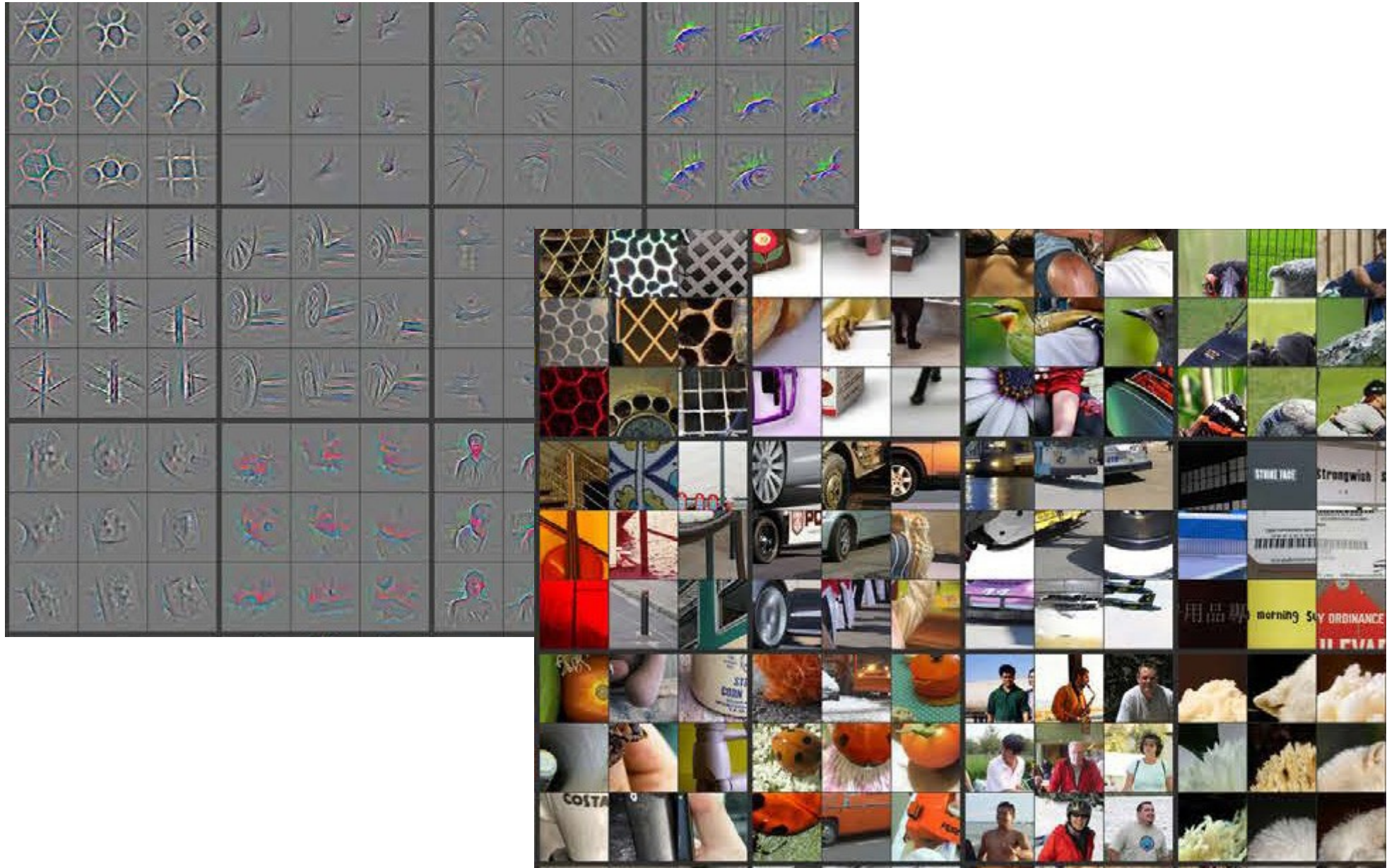


Alchemy or Chemistry?

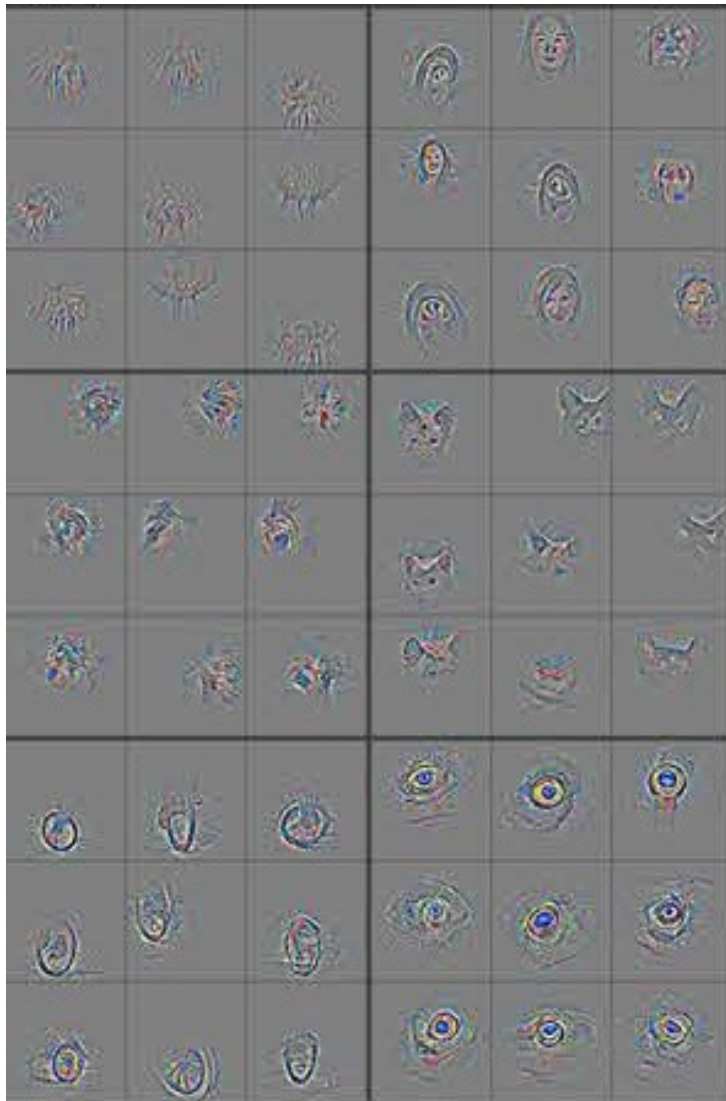
deepvis



deepvis



deepvis

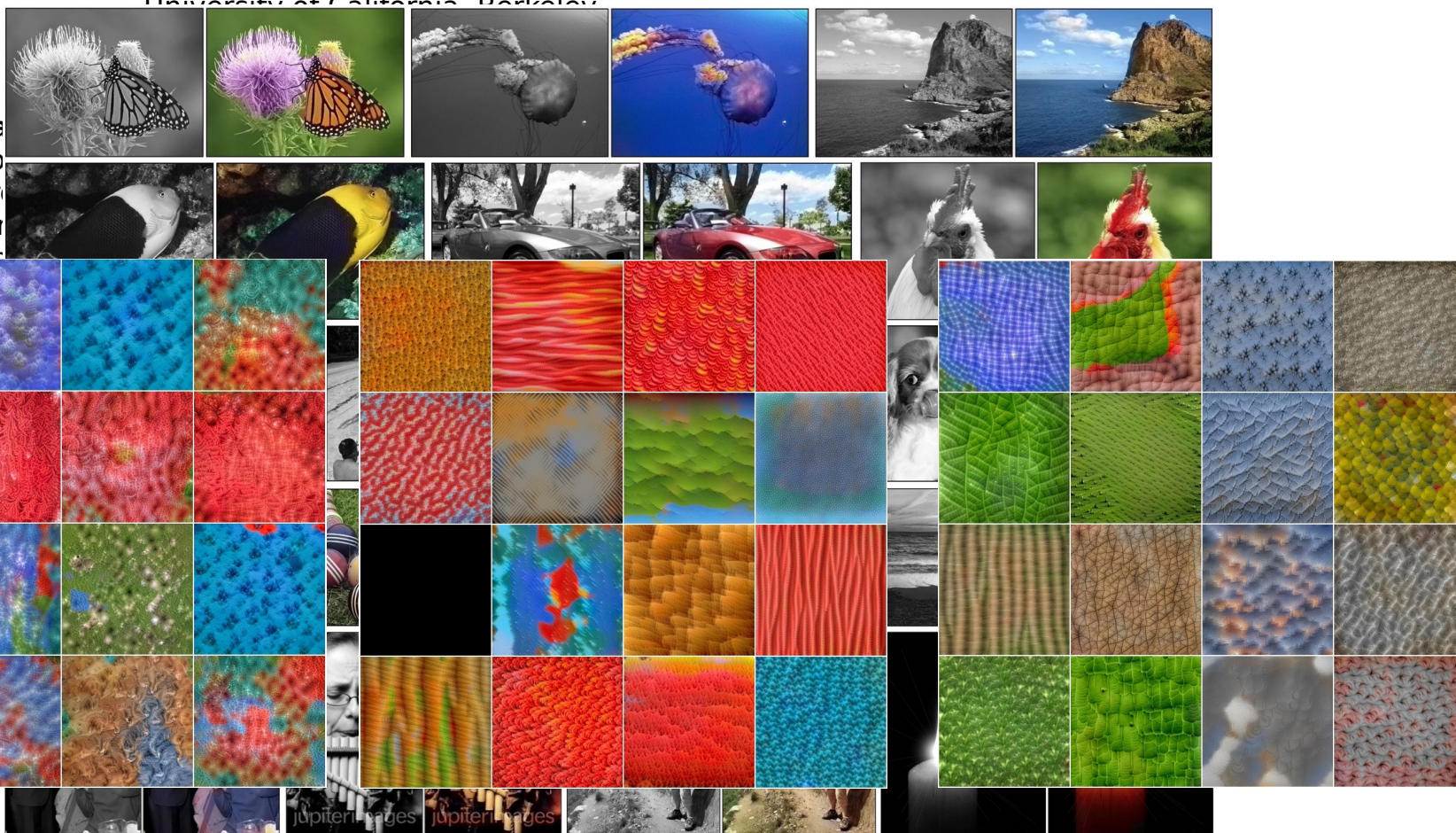


Colorful Image Colorization

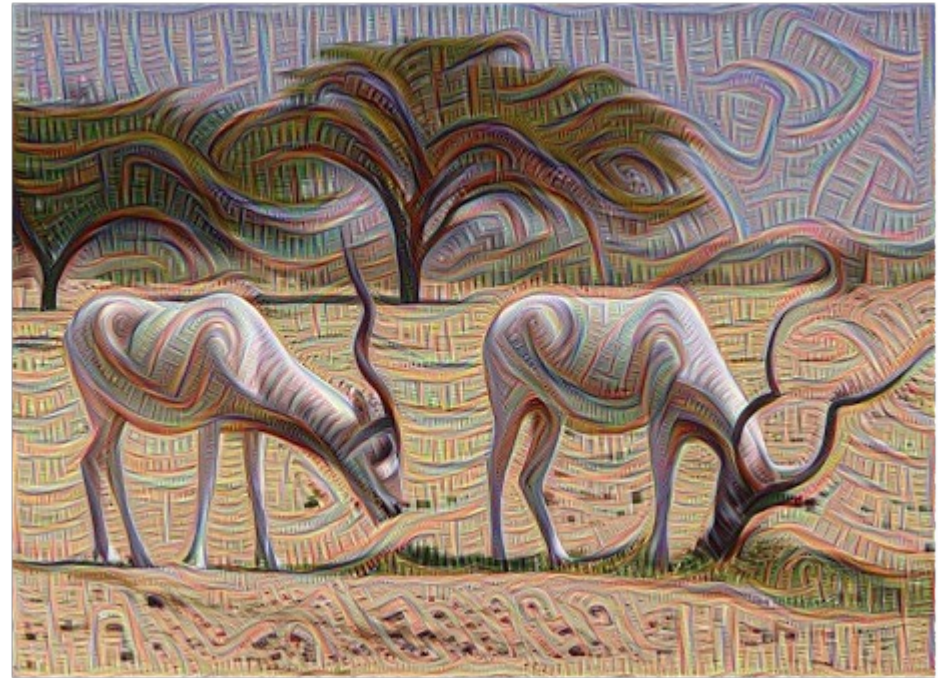
Richard Zhang, Phillip Isola, Alexei A. Efros
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University of California, Berkeley

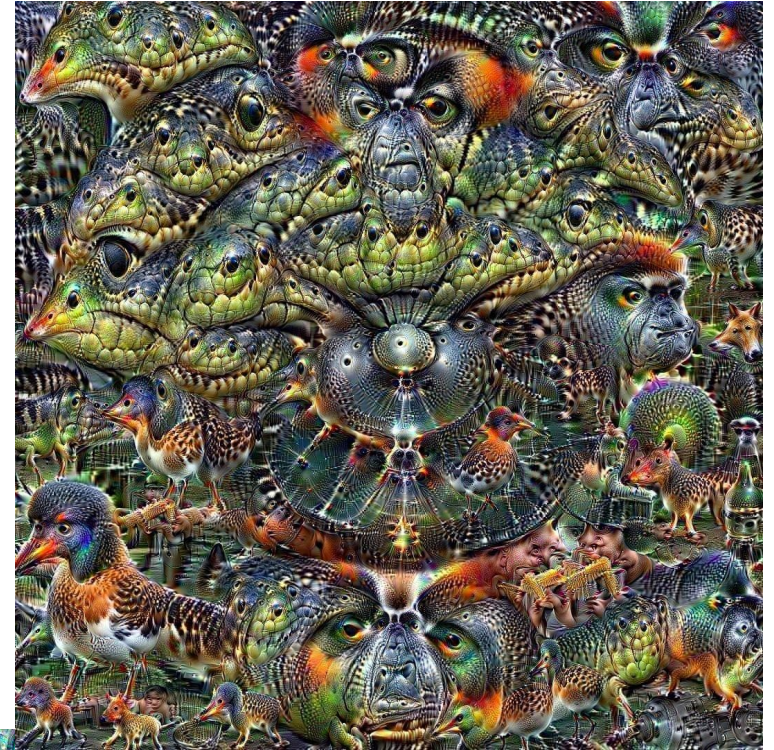
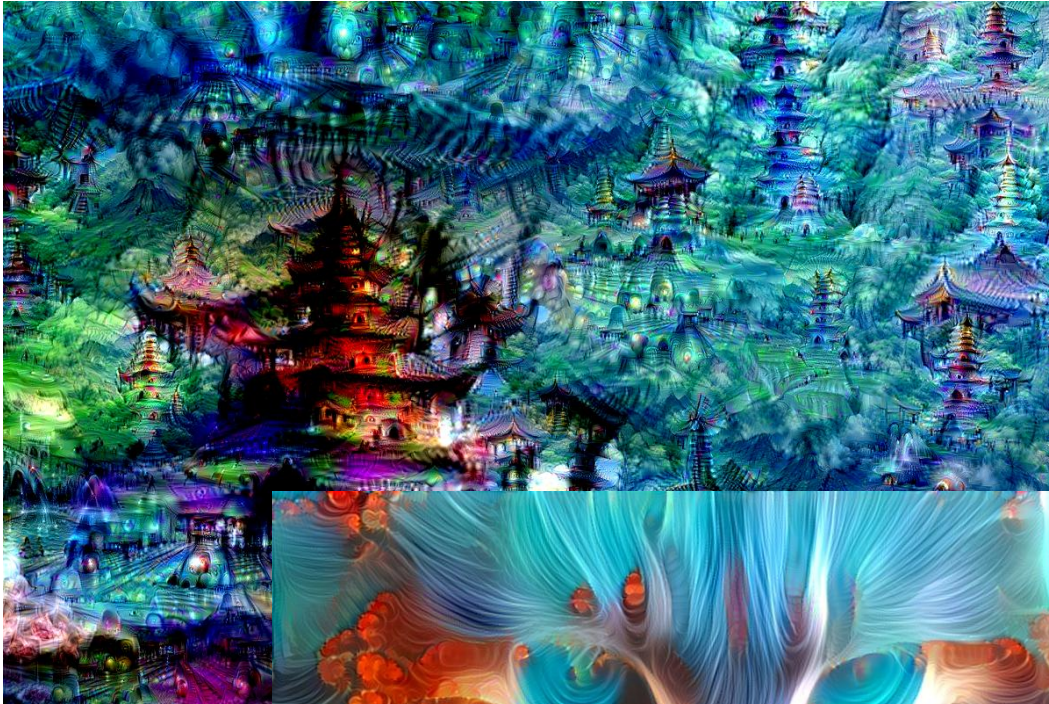
Abstract
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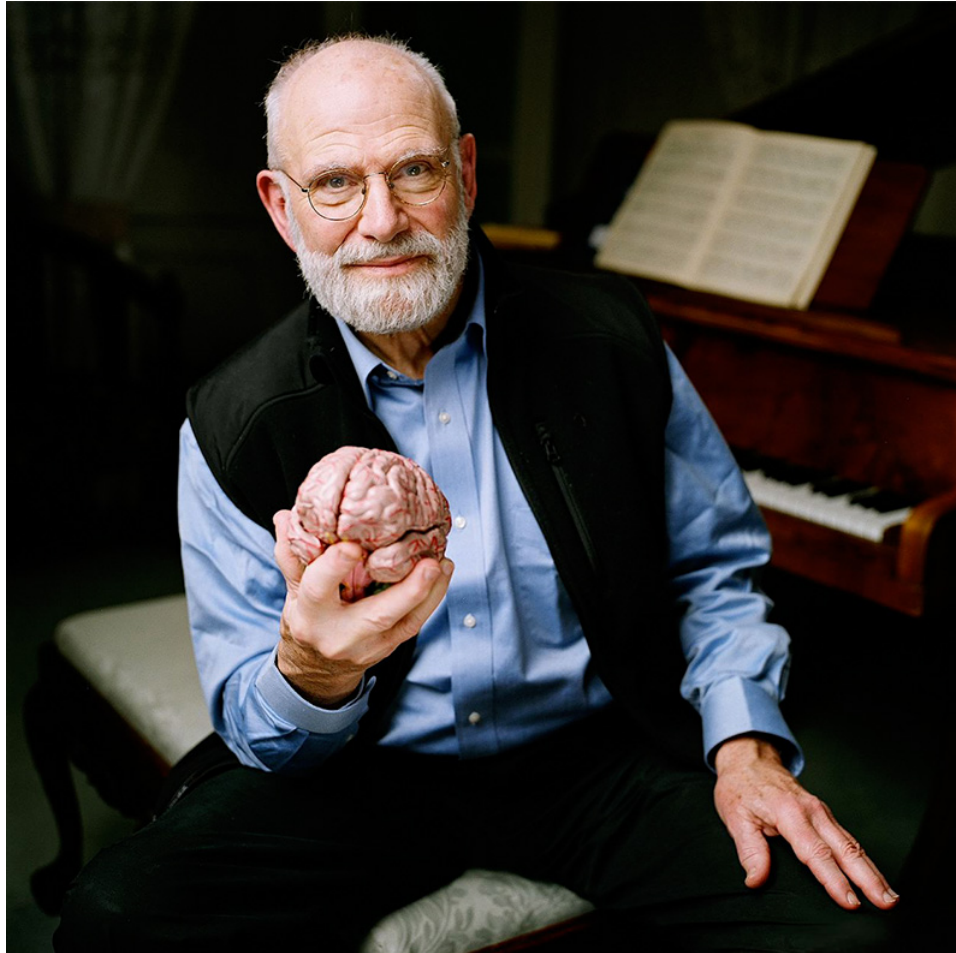
deep dreams



deep dreams

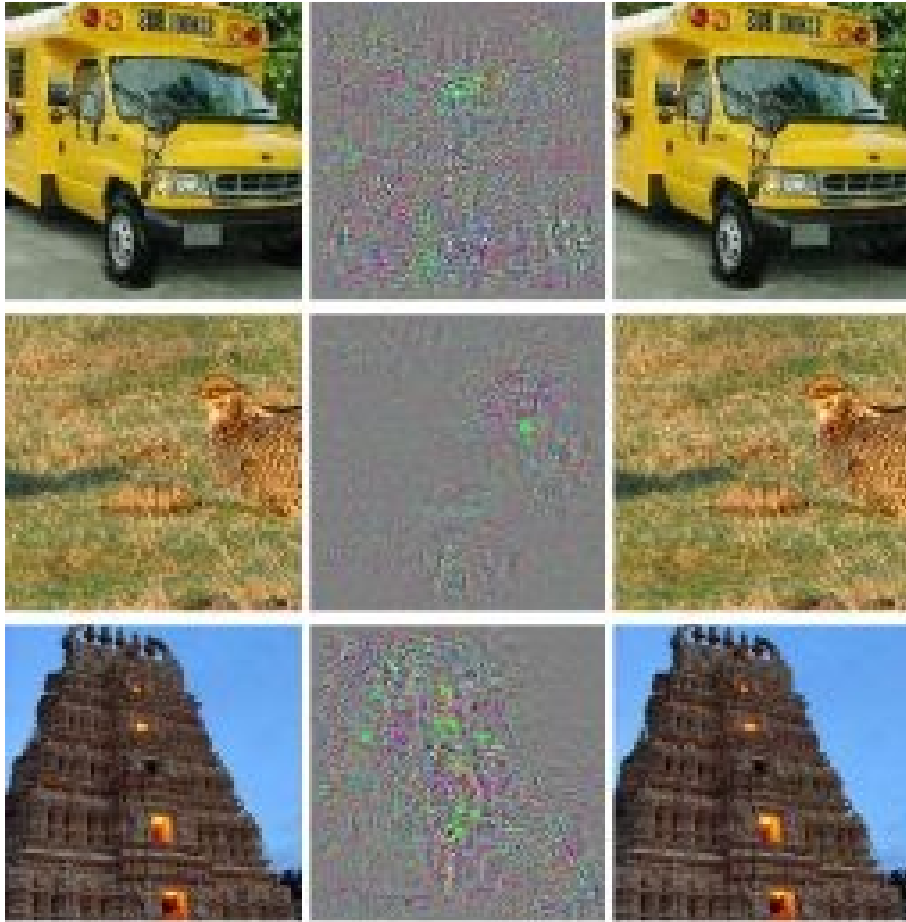


real deep dreams?

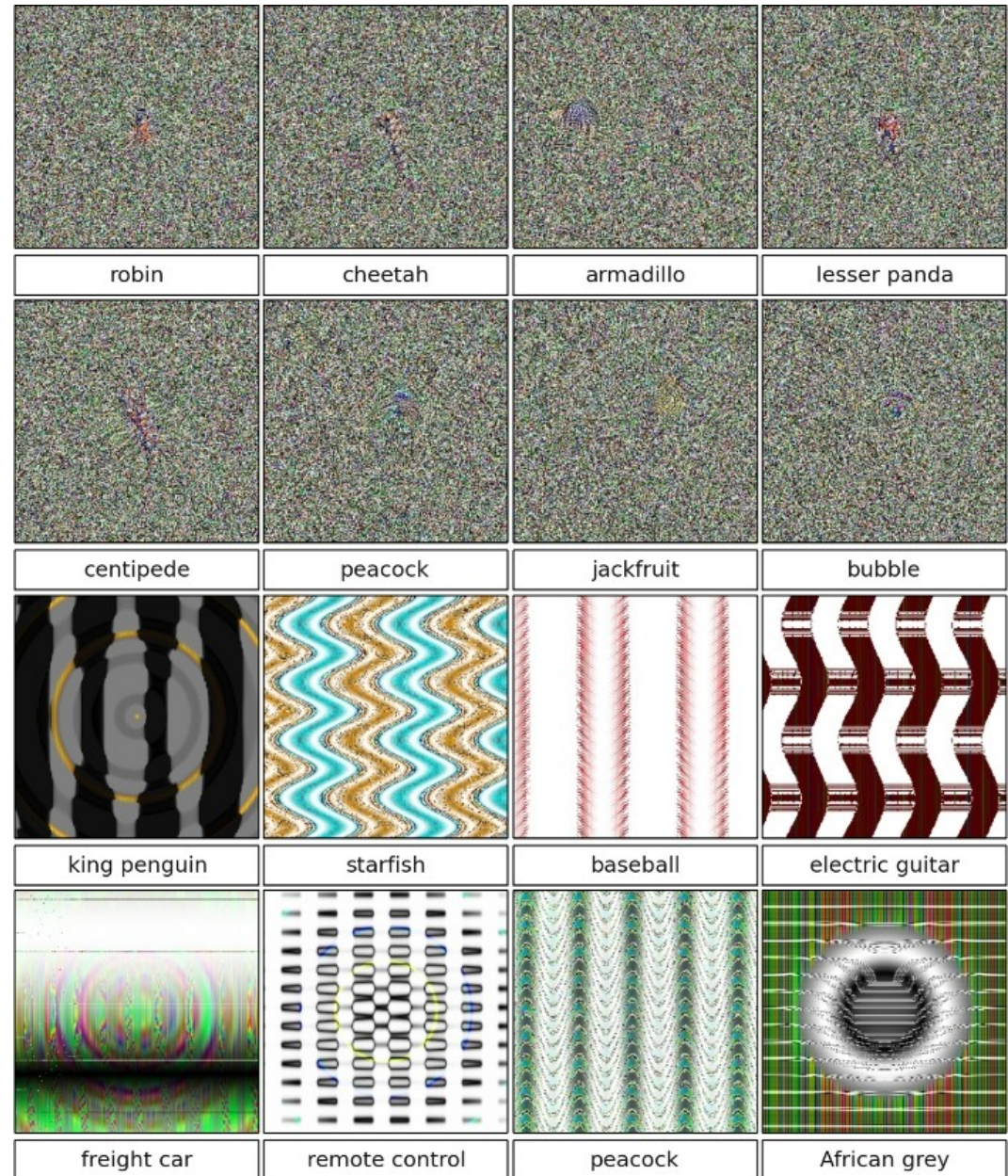
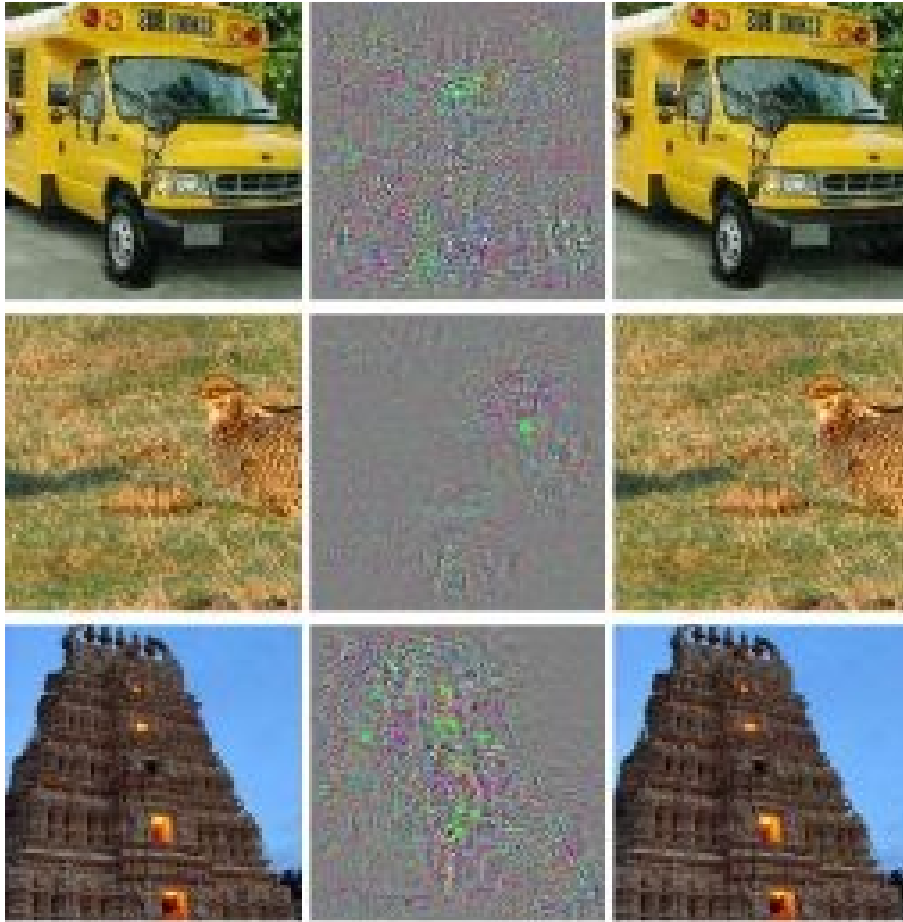


https://www.ted.com/talks/oliver_sacks_what_hallucination_reveals_about_our_minds

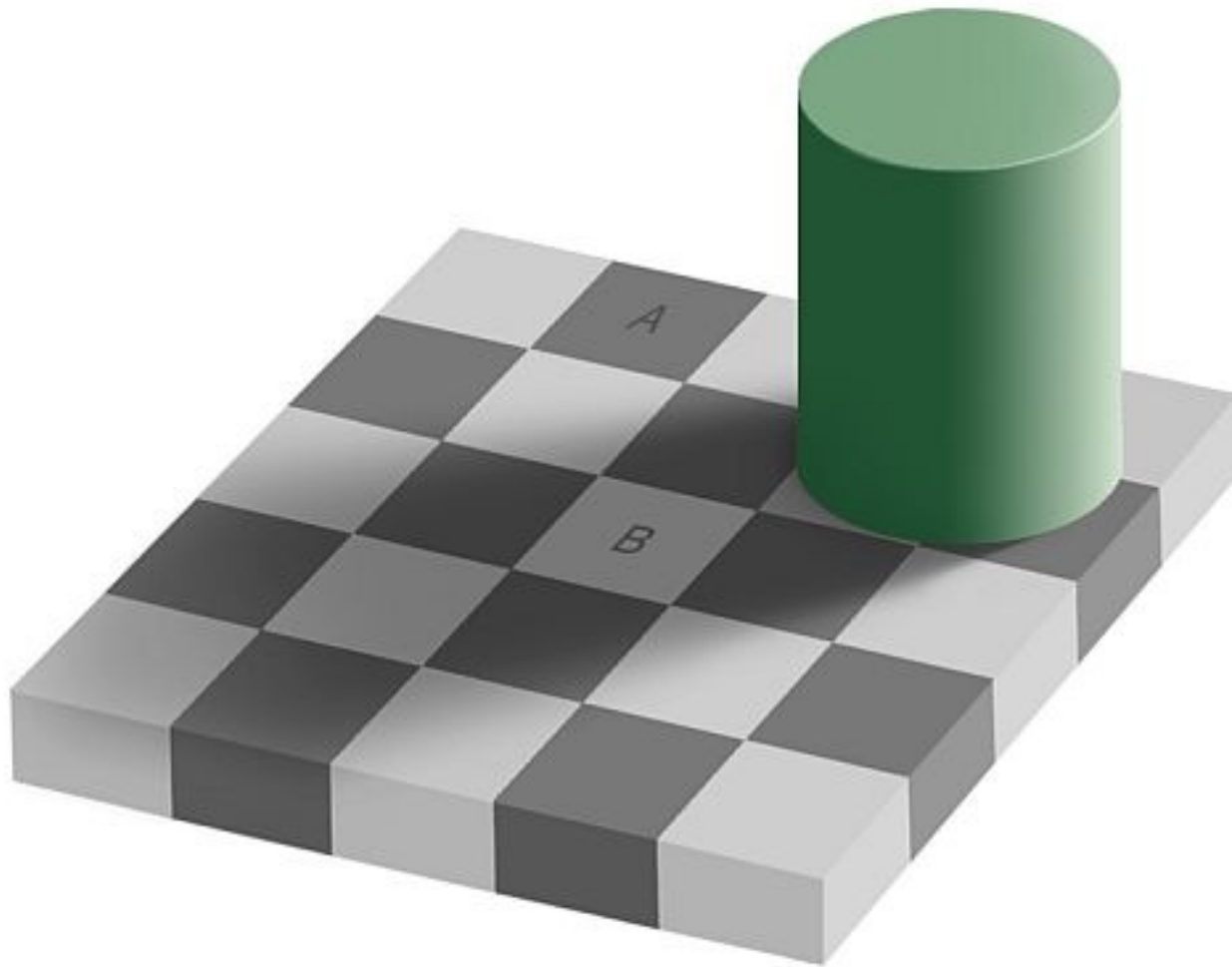
human vs machine



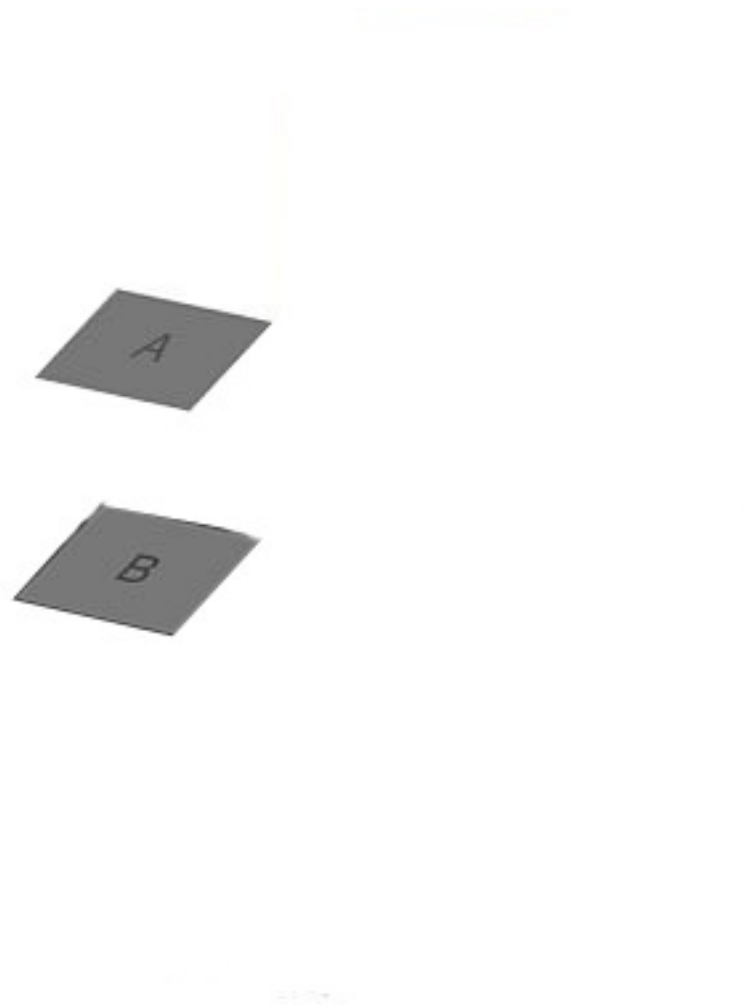
human vs machine



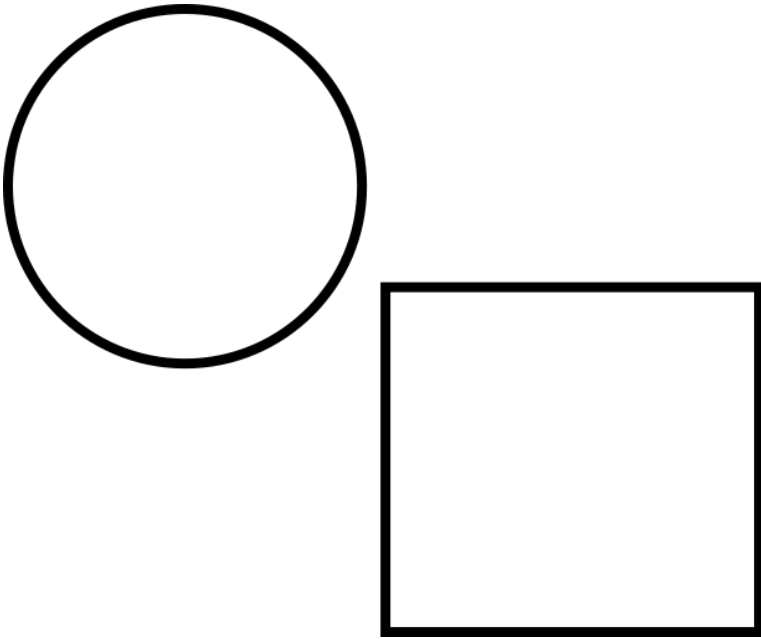
human vs machine



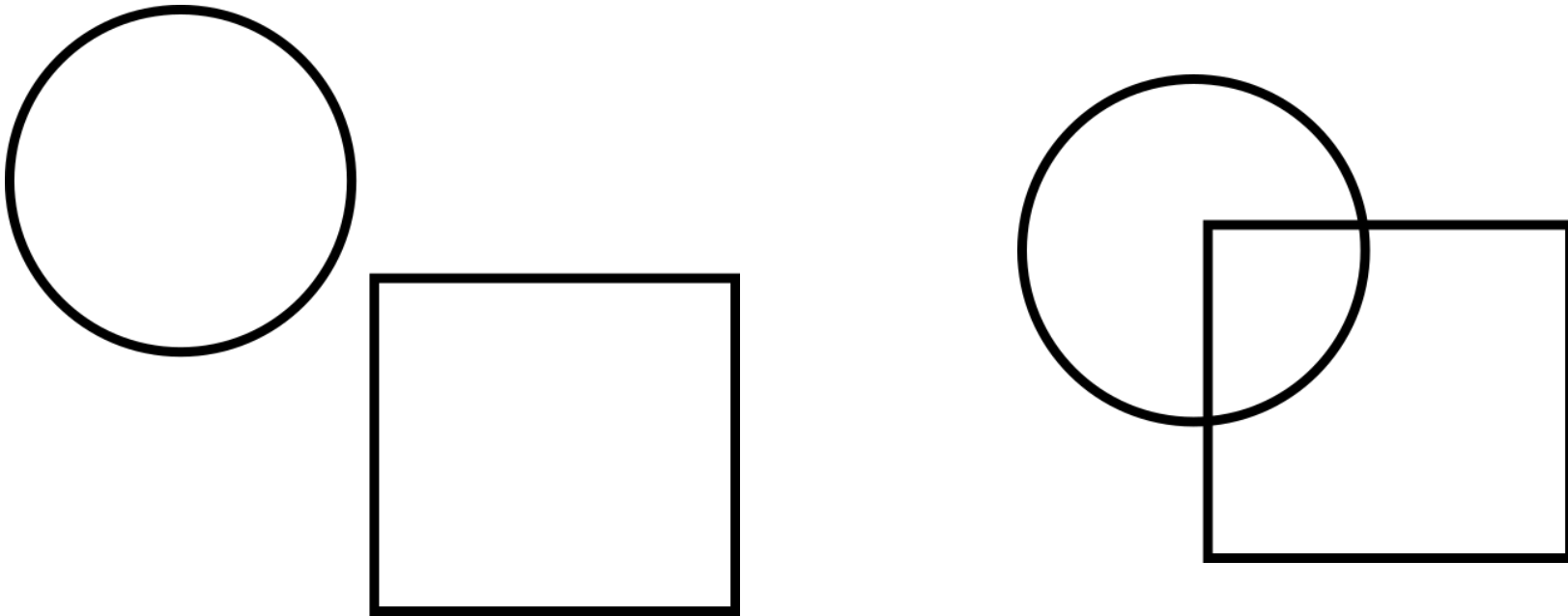
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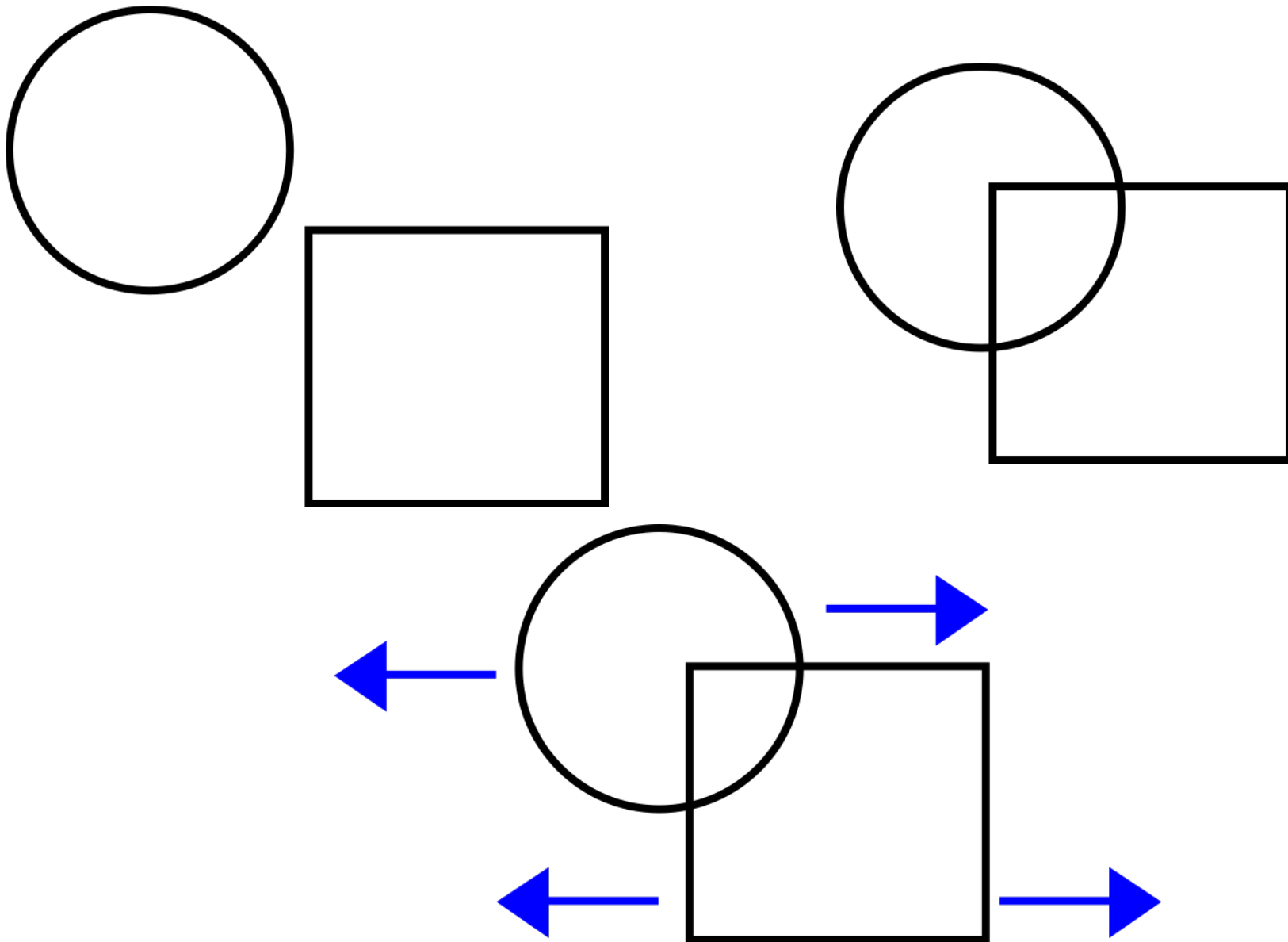
learning to see



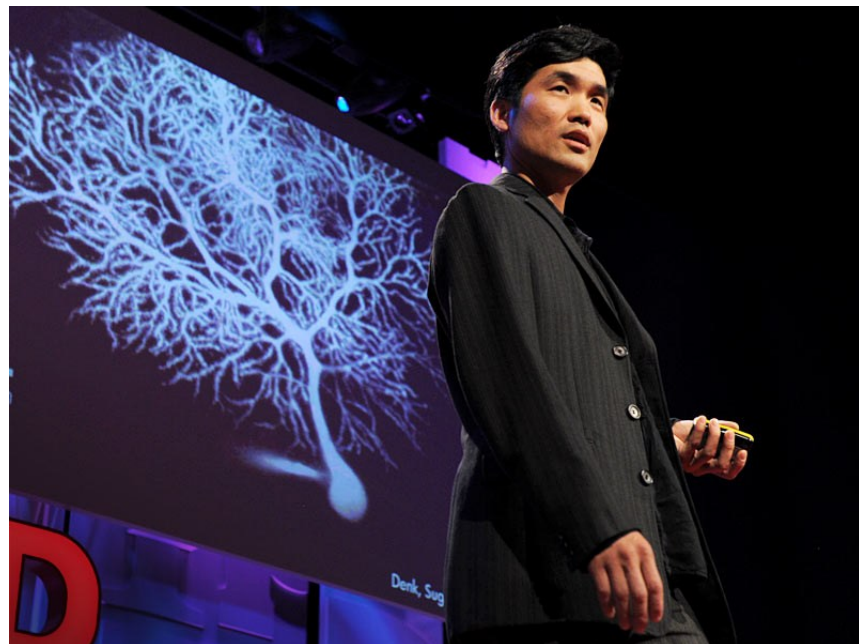
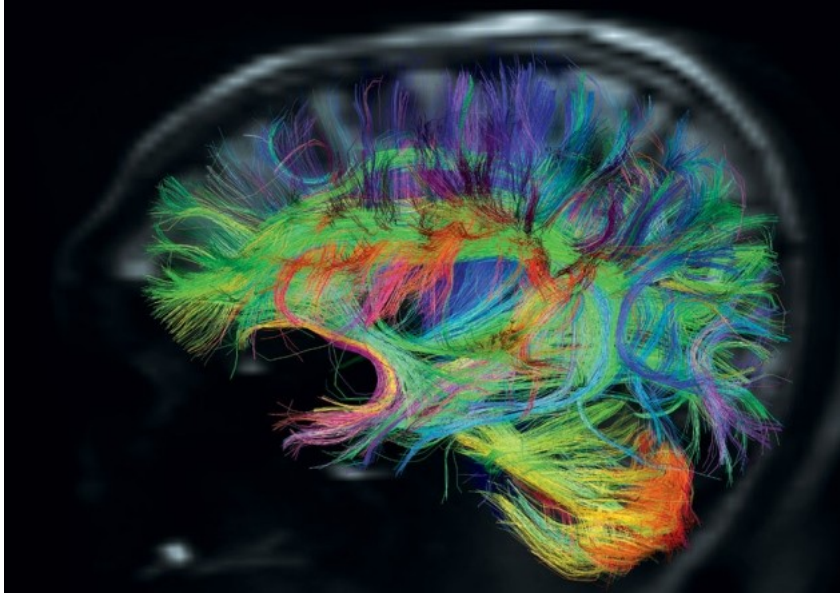
learning to see



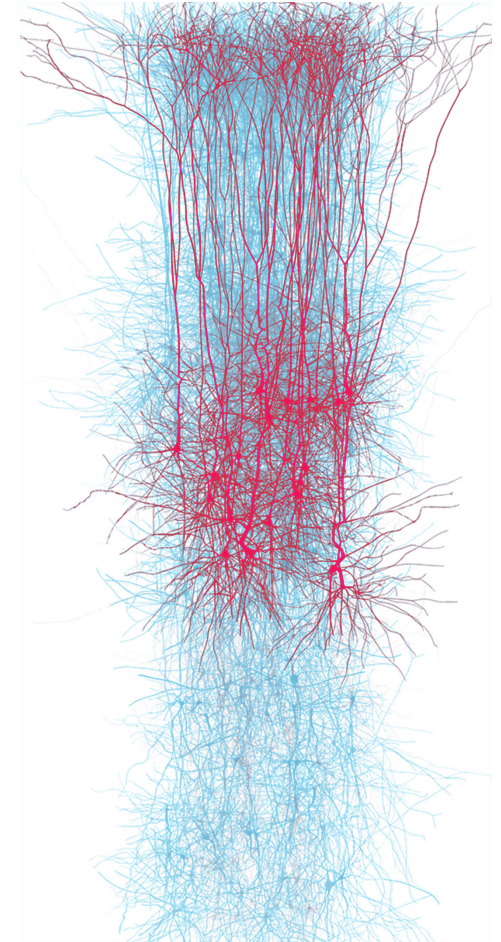
learning to see



connectome



Blue Brain Project



https://www.ted.com/talks/henry_markram_supercomputing_the_brain_s_secrets
https://www.youtube.com/watch?time_continue=2&v=2qTuZIMvFgY

The Big and the Small: Challenges of Imaging the Brain's Circuits

Jeff W. Lichtman^{1*} and Winfried Denk^{2*}

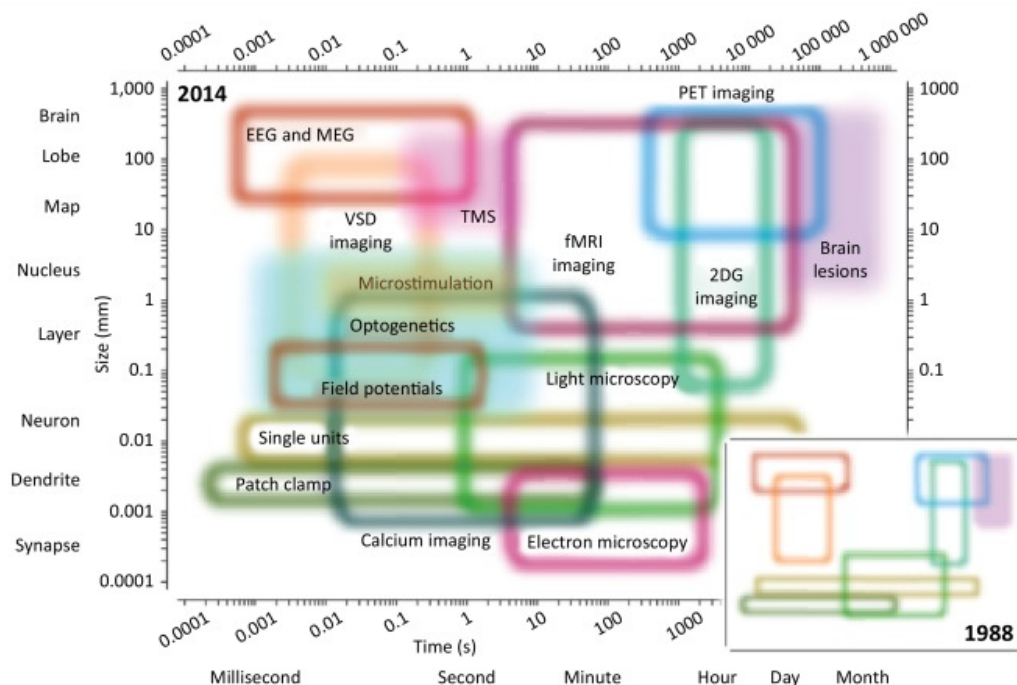
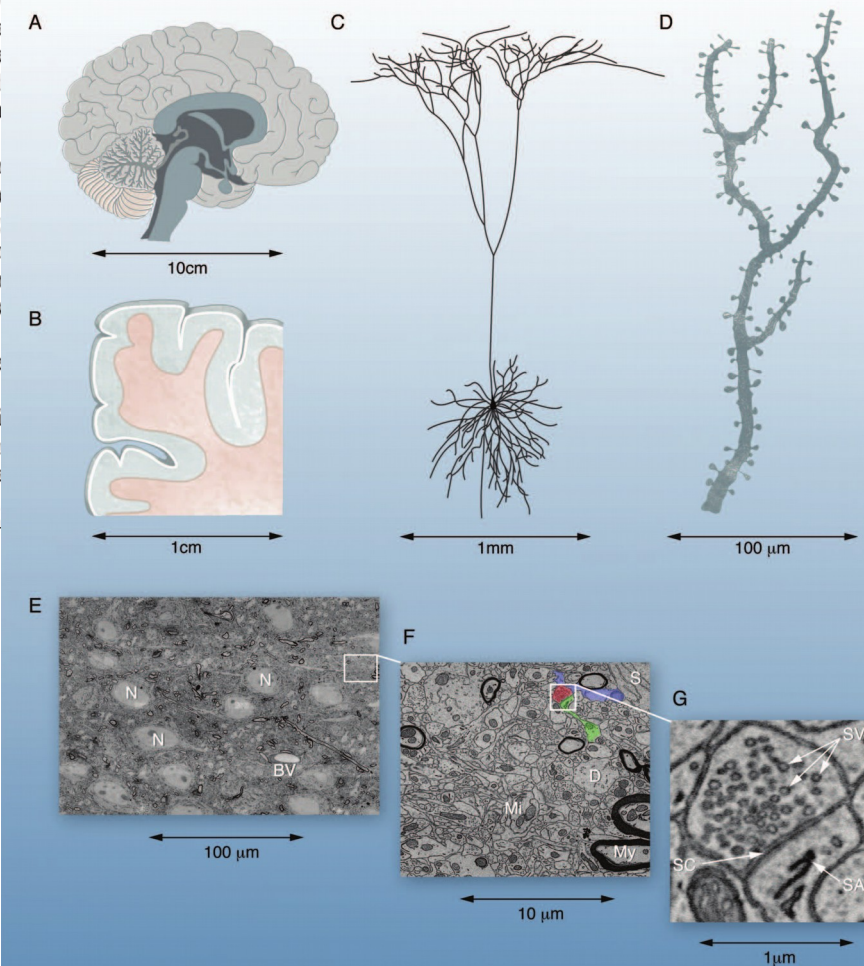
The relation between the structure of the nervous system and its function is more poorly understood than the relation between structure and function in any other organ system. We explore why bridging the structure-function divide is uniquely difficult in the brain. These difficulties also explain the thrust behind the enormous amount of innovation centered on microscopy in neuroscience. We highlight some recent progress and the challenges that remain.

A central theme of biology is the relation between the structure and function of things. By structure, we mean the physical form of something, a property that humans can apprehend by touch (if the object is big enough) or by sight. Right now, the leading edge of this effort is the field known by the general name “structural biology” but is focused

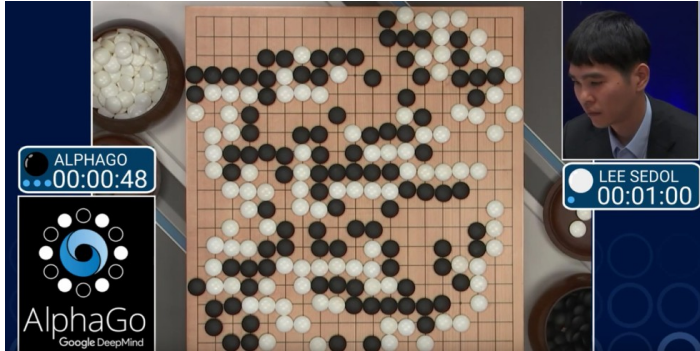
tem, where much progress has been made at the molecular and functional level. But notwithstanding the extraordinary insights of neurobiology’s foremost structural biologist, Cajal, our understanding of the relation between the structure and function of the brain remains primitive, especially when compared to other organ systems. There is no other organ system where so

research to determine the full extent of cell-type diversity in this small part of the nervous system, because the range of cell types continues to grow as the analysis becomes more refined. Moreover, neuronal cell one region to brain serves a itself. Few of retinal cell in trying to u bral cortex.

Researcher diversity by ities to categor basis of the n molecular bio generating tis cent markers of neuronal ce is clear: The thesis of inhib only in inhib molecular m derstood (4).



applications



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Google's Neural Machine Translation

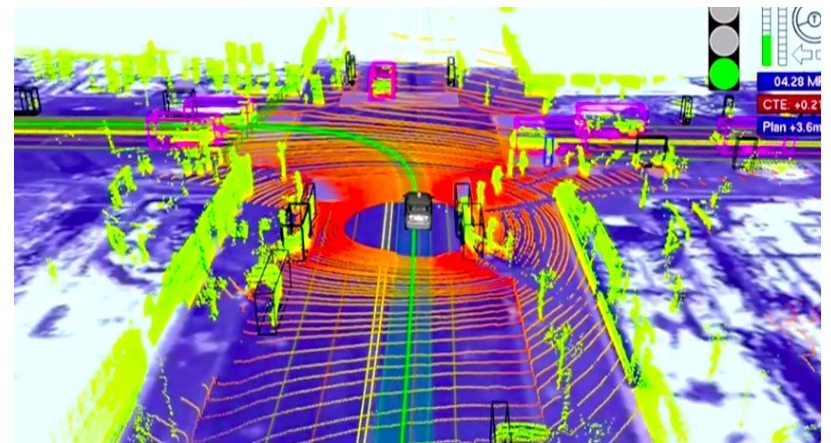
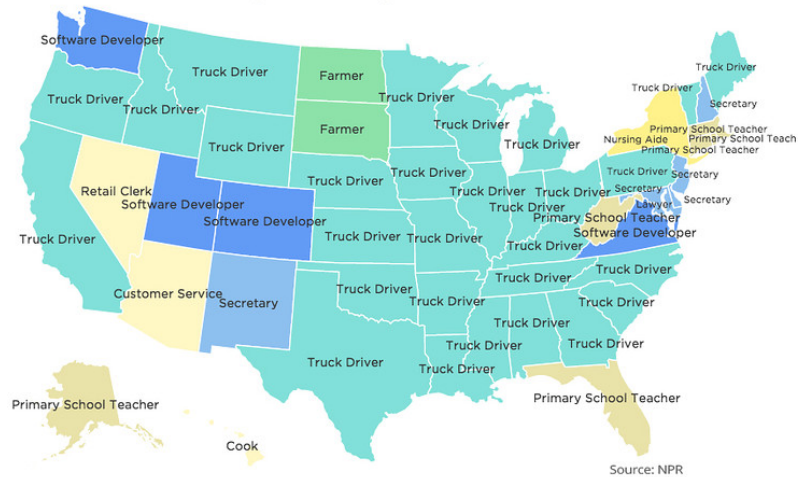
...reduced translation errors by an average of 60% when compared to the prior Google Translate technology

Learning Deep Learning
fast.ai course

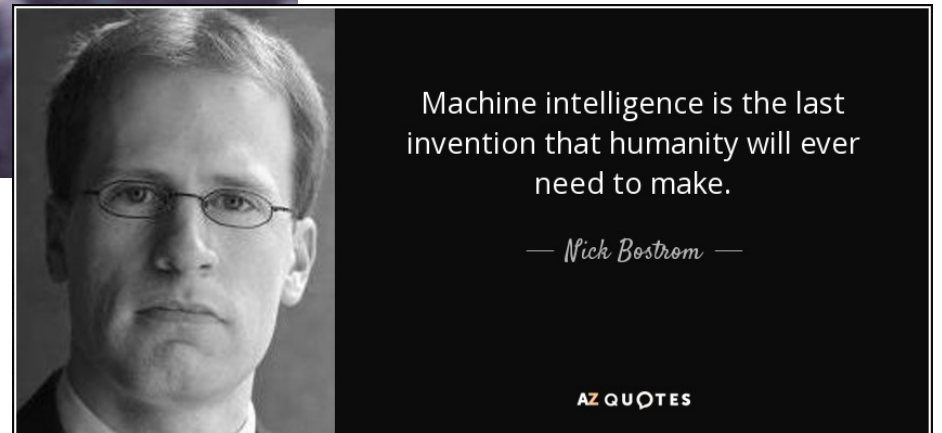
Teemu Kurppa - www.teemukurppa.net
Head of Cloud , OURA - ouraring.com
Twitter - @teemu

<http://www.fast.ai/>

Moshe Vardi



Nick Bostrom



https://www.ted.com/talks/nick_bostrom_what_happens_when_our_computers_get_smarter_than_we_are

See eye to eye!

Ricardo Marroquim

www.lcg.ufrj.br/marroquim



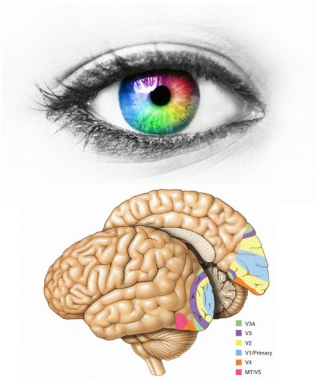
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de Sistemas e Computação



<https://vimeo.com/132700334>

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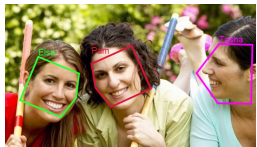
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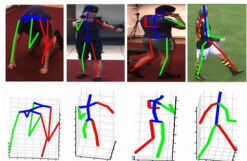
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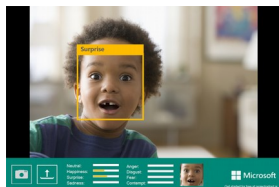
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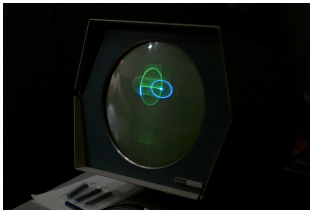


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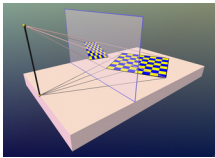
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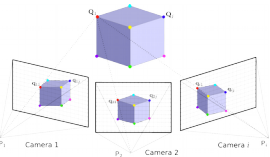
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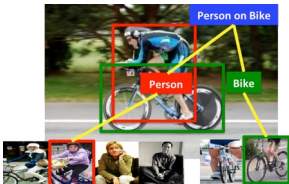
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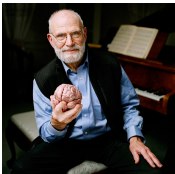
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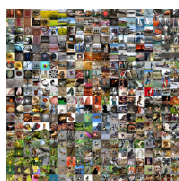


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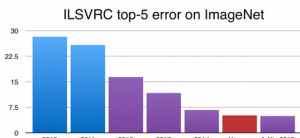
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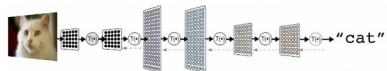
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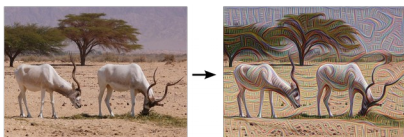
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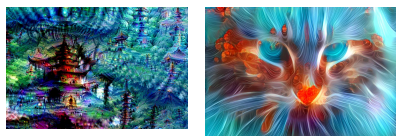
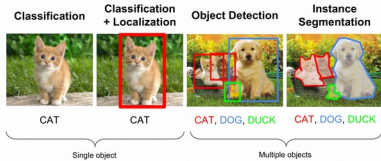
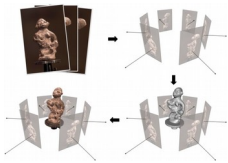


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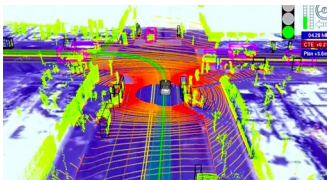
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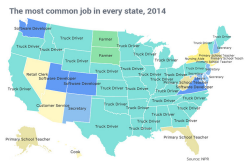
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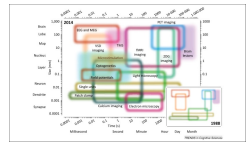
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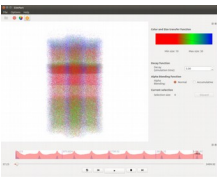
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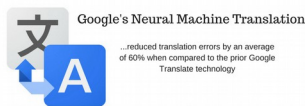
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